HIPOT Tester
19071/19072/19073
User’s Manual

Version 1.4
September 2004
P/N A11 000787
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The Danger of Operating

1. When the instrument is under output voltage, please don’t touch test area or you may shock hazard and result in death.

   Please obey the following items.
   • Make sure the grounding cable is connected correctly and using the standard power cord.
   • Don’t touch the output terminal.
   • Don’t touch test cable of connecting test termination.
   • Don’t touch test termination object.
   • Don’t touch any charge component of connecting output terminal.
   • As the instrument end the test or turn off output, please don’t touch test unit immediately.

2. The shock accidents are usually occurred on the following conditions.
   • The grounding terminal of the instrument doesn’t connect correctly.
   • No use insulation glove for testing.
   • After test is completed to touch test unit immediately.

3. Remote control for the instrument: This instrument provided with remote control, normally using the external signal to control high voltage output. For safety reasons and prevent from hazards, please exactly follow instructions below while using remote control.
   • Unexpected high voltage output may exist. Make sure if this instrument is under testing/remote controlling before access to the probes.
   • When the instrument is under testing/operating, any access to DUT, test cable and probe output terminal are prohibited, both for the operator/service personnel.
   • Normally remote control of this instrument is controlled by the high voltage test bar. However, using of other control circuit is also possible. For safety reasons and prevent from hazards, please notice that unintentional access to the control test bar or bridging the control circuit to high voltage terminal and test cables may cause hazards. Please keep this terminal/control from unintentional bridging/access to avoid danger.
Storage
When don’t use the device, please pack it properly and store under a good environment. (The packing is no needed when the device under appropriate environment.)

Freight
Please use the original packing material when move the device. If the packing material is missing, please use the equivalent buffer material to pack and mark it fragile and waterproof etc to avoid the device damage during movement. The device belongs to precise equipment, please uses qualified transportation as possible. And avoid heavy hitting etc to damage the device.

Maintenance
There is no maintenance operation for the general user. (Except for the note in the manual.) Please contact our company or agent when the device occurred the user judgment abnormal. Don’t maintain by yourself to avoid occurred unnecessary danger and serious damage to the device.

Disposal
When the device in badly condition and can’t be used or repaired, please discard it according to your company disposal procedures or local legal procedures. Don’t discard arbitrary to avoid polluting environment.
## Revision History

The following lists the additions, deletions and modifications in this manual at each revision.

<table>
<thead>
<tr>
<th>Date</th>
<th>Version</th>
<th>Revised Sections</th>
</tr>
</thead>
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<tr>
<td>Jan. 2003</td>
<td>1.0</td>
<td>Complete this manual.</td>
</tr>
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</table>
| April 2003 | 1.1     | Modify "Specifications (18°C ~ 28°C RH ≤ 70%)"
          |          | - "Standard Accessory"
          |          | - "Rear Panel"
          |          | - "RS-485 Interface"
          |          | - "Solving Problems"                                  |
| Dec. 2003  | 1.2     | Modify "Introduction"
          |          | - "Rear Panel"
          |          | - "Operation"
          |          | - "Auto Range"
          |          | - "Calibration Procedure"
          |          | - "Command Description"
          |          | Delete "RS-485 Interface"                             |
          |          | Add "RS485 Interface (Optional)"                       |
| March 2004 | 1.3     | Add "The Danger of Operating"
          |          | - "Storage. Freight. Maintenance. Disposal"           |
          |          | Modify "Specifications (18°C ~ 28°C RH ≤ 70%)"
          |          | - "Rear Panel"                                        |
| Sep. 2004  | 1.4     | Modify "Product Features"
          |          | - "Optional Accessory"
          |          | - "Rear Panel"
          |          | - "PROGRAM Parameter Setting"
          |          | - "How to Perform Tests"
          |          | - "RS485 Interface (Option)"                           |
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1. **Introduction**

1.1 **An Overview of Function**

- This high quality automatic HiPot test instrument is designed to test the withstanding leakage current and insulation resistance for electric machinery and electronic devices.

- For withstanding test, its output power is AC: 100VA (5kV, 20mA), DC: 30VA (6KV, 5mA), which is applicable to electronic, electric machinery and components for withstanding and insulation tests.

- For insulation resistance, its test range is from 0.1MΩ~50GΩ, and test voltage is 0.050kV ~1kV definable.

- For ground continue, its test range is from 0Ω~5Ω.

- All settings for state, time, current, voltage and resistance can be seen clearly on the display. There is no need to memorize the parameter state of any items.

- It is equipped with devices for Pass/Fail judgment, test results and remote control.

- It can perform high efficiency and accurate tests for electric machinery, electronic devices and components.

1.2 **Product Features**

- **Multiple Test States**
  This instrument can select a single item for test, such as AC withstanding test, DC withstanding test, insulation resistance test and ground continue test.

- **Clear Display**
  This instrument has the clearest design for setting the parameters of test voltage, current states, readings, procedures and states. All of them can be read from the display directly.

- **High/Low Limit Comparator for Pass/Fail Judgment**
  The function of high/low limit comparator for Pass/Fail judgment is designed for both withstanding and insulation resistance test. The HiPot low limit comparator and insulation high limit comparator are generally designed to prevent the misjudgment due to bad connection or test cable tripped. This function is able to detect if there is any bad connection or broken line.

- **Remote Control**
  This instrument can extend [START] and [RESET] signals to control externally. Usually they are connected to high voltage test gun or control case.

- **Changing the Time for Voltage Rising**
  This instrument contains [RAMP] function. This function is to change the time required
for the outputted test voltage from zero rising to the specified value.

- **Changing the Time for Voltage Falling**
  This instrument contains [FALL] function. This function is to change the time required for the outputted test voltage from the specified value falling to zero.

- **Current Range Auto Switch**
  There are two HiPot test AC ranges, one is low AC range 0 ~ 3.000mA, the other is AC 3.01~20mA. There are three DC ranges, low current range 0 ~ 300uA, current range 0.301mA ~ 3mA and current range 3.01mA ~ 5.00mA. When the testing current is small, you can set if to switch the current range to the low one automatically for higher resolution via software as need.

- **RS-485 Interface Multi-Link Test (For link test model of 19073 + RS485 only)**
  The tester and PC that installed RS485 interface card performs link test. The maximum is 31 sets of instruments to process link test with PC mainframe simultaneously. Also, PC mainframe can control the setting and read the test data. When there is no PC mainframe, multi-link test can be performed individually but the test data can’t be read.
### 1.3 Specifications (18°C ~ 28°C RH ≤ 70%)

<table>
<thead>
<tr>
<th>Specification</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Withstanding Voltage Test</strong></td>
<td></td>
</tr>
<tr>
<td>Test Voltage</td>
<td>AC: 0.05<del>5kV / DC: 0.05</del>6kV Constant Voltage (19072, 19073 only)</td>
</tr>
<tr>
<td>Voltage Regulation</td>
<td>≤ 1%+5V, Rated Load</td>
</tr>
<tr>
<td>V-display Accuracy</td>
<td>± (1% of reading + 5 counts), 2V resolution</td>
</tr>
<tr>
<td>Cutoff Current (Note1)</td>
<td>AC: 0.1mA ~ 20mA, DC: 0.01mA ~ 5mA (Note1), 0.1uAdc resolution</td>
</tr>
<tr>
<td>I-display Accuracy (Note1)</td>
<td>± (1.5% of reading + 5 counts) (Note2) WDC only</td>
</tr>
<tr>
<td></td>
<td>± (1.5% of reading + 5 counts) (Note2)</td>
</tr>
<tr>
<td>Output Frequency</td>
<td>50Hz, 60Hz</td>
</tr>
<tr>
<td>Test Time</td>
<td>0.1 ~ 999 Sec, continue (Note3)</td>
</tr>
<tr>
<td>Dwell Time</td>
<td>0.1 ~ 999 Sec, off</td>
</tr>
<tr>
<td>Ramp Time</td>
<td>0.1 ~ 999 Sec, off (0.1sec approx.)</td>
</tr>
<tr>
<td>Fall Time</td>
<td>0.1 ~ 999 Sec, off</td>
</tr>
<tr>
<td><strong>Arc Detection</strong></td>
<td></td>
</tr>
<tr>
<td>Setting Mode</td>
<td>Programmable Setting</td>
</tr>
<tr>
<td>Detection Current</td>
<td>AC: 1mA ~ 20mA, DC: 1mA ~ 5mA</td>
</tr>
<tr>
<td>Min. pulse width</td>
<td>10us approx.</td>
</tr>
<tr>
<td><strong>GOOD/NO-GO Judgment Function</strong></td>
<td></td>
</tr>
<tr>
<td>Judgment System</td>
<td>Window comparator</td>
</tr>
<tr>
<td></td>
<td>A NO-GO judgment is made when a current greater than the high limit value or smaller than the low limit value is detected.</td>
</tr>
<tr>
<td></td>
<td>When a NO-GO judgment is made, the output voltage is cut out and a NO-GO alarm signal is delivered.</td>
</tr>
<tr>
<td></td>
<td>If no abnormal state is detected during the test time a GOOD Judgment is made and a GOOD signal is delivered.</td>
</tr>
<tr>
<td><strong>Insulation Resistance Test (19073 only)</strong></td>
<td></td>
</tr>
<tr>
<td>Test Voltage</td>
<td>DC: 0.05kV ~ 1kV, Constant Voltage</td>
</tr>
<tr>
<td>V-display Accuracy</td>
<td>± (5% of reading + 5 counts) (open voltage), 2V resolution</td>
</tr>
<tr>
<td>Resistance Range</td>
<td>0.1 MΩ ~ 50 GΩ (Note 4)</td>
</tr>
<tr>
<td>Measuring Accuracy</td>
<td>≥ 500V: 1MΩ ~ 1000MΩ: ± 4% + 5 counts</td>
</tr>
<tr>
<td></td>
<td>1GΩ ~ 10GΩ: ± 7% + 5 counts</td>
</tr>
<tr>
<td></td>
<td>10GΩ ~ 50GΩ: ± 12% + 5 counts</td>
</tr>
<tr>
<td></td>
<td>&lt; 500V: 0.1 MΩ ~ 1000MΩ: ± 7% + 5 counts</td>
</tr>
<tr>
<td></td>
<td>&lt; 100V: 0.1 MΩ ~ 1000MΩ: ± 10% + 5 counts</td>
</tr>
<tr>
<td><strong>Secure Protection Function</strong></td>
<td></td>
</tr>
<tr>
<td>Fast Output Cut-off</td>
<td>Approx. 0.4mS, after NG happen</td>
</tr>
<tr>
<td>Fast Discharge</td>
<td>Approx. 0.2S, Typical</td>
</tr>
<tr>
<td>Ground Fault Interrupt</td>
<td>0.5mA ± 0.25mAac (ON), OFF</td>
</tr>
<tr>
<td>Continuity Check</td>
<td>0.1Ω ~ 5.0Ω ± 0.2Ω, GC MODE</td>
</tr>
<tr>
<td>Panel Operation Lock</td>
<td>YES</td>
</tr>
<tr>
<td><strong>Memory Storage</strong></td>
<td></td>
</tr>
<tr>
<td>Memories, Steps</td>
<td>10 steps or 60 groups for total 60 memory location</td>
</tr>
<tr>
<td><strong>GO/NG Judgment Window</strong></td>
<td></td>
</tr>
</tbody>
</table>
## Indication, Alarm
- **GO:** (Short Sound)
- **NG:** W-Arc, W-Hi, W-Lo, IR-Lo, IR-Hi, GFI (Long Sound)

## Remote Connector
- **Rear Panel 9 Pin D-type Connector**
  - **Input:** Start, Stop, Interrupt
  - **Output:** Under test, Pass, Fail

## TEST/RESET Control
- **Low - active control (24V open voltage typical).**
- **Input requirements:**
  - **Input time duration:** 20msec. approx
  - The above input circuits are not isolated from other internal circuits.

## Options (RS485 only)
- **RS-485 Interface**
  - A maximum of 32 devices connected to each bus

## Ambient Temperature and Relative Humidity
- **Specifications range**
  - 18 to 28°C (64 to 82°F), \( \leq 70\% \text{ RH} \).
- **Operable range**
  - Maximum relative humidity 80% for temperature up to 31°C (88°F). Decreasing linearly to 50% relative humidity at 40°C (104°F)
- **Storage range**
  - -10 to 60°C (-14 to 140°F), \( \leq 80\% \text{ RH} \).

## Power Requirement
- **Line Voltage**
  - AC 100V, 120V, 220V ± 10%, 240V +5 -10%
- **Frequency**
  - 50 or 60 Hz
- **Power**
  - No load: < 60W
- **Consumption**
  - With rated load: 300W max.

## General
- **Dimension**
  - 270(W) x 105(H) x 350(D) mm
- **Weight**
  - Approx 12kg

## Safety
- **Ground Bond**
  - Less than 100mΩ at 25Amp, 3sec
- **Hipot**
  - Less than 10mA at 1.8kVac, 3sec
- **Insulation Resistance**
  - Over 100MΩ at 500V 3sec
- **Line leakage current**
  - Less than 3.5mA at 127V, 3sec, normal, reverse

---

**Note 1:** AC set over 75VA, DC set over 22.5VA the maximum operating time is 60seconds, and the rest time is the same. If period of rest time is 1/2 duty of operating time. For full rating output, the line input range is +10% ~ -0%.

**Note 2:** Only refer to 1.2kV resistance load.

**Note 3:** IR test time range is 0.3 sec ~ 999 sec.

**Note 4:** Display resistance range is up to 60GΩ.
1.4 Standard Accessory

<table>
<thead>
<tr>
<th>Item</th>
<th>Part Number</th>
<th>Q’ty</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power Cord</td>
<td>W12 010130</td>
<td>1</td>
<td>Line cord</td>
</tr>
<tr>
<td>3P – 2P Adapter</td>
<td>N31 000039</td>
<td>1</td>
<td>Power cord adapter</td>
</tr>
<tr>
<td>Test Cable (1)</td>
<td>W38 001940</td>
<td>1</td>
<td>Withstanding test cable for HIGH terminal</td>
</tr>
<tr>
<td>Test Cable (2)</td>
<td>W38 001760</td>
<td>1</td>
<td>Withstanding test cable for LOW terminal</td>
</tr>
<tr>
<td>Test Cable (3)</td>
<td>W38 001930</td>
<td>1</td>
<td>Ground continuity test cable</td>
</tr>
<tr>
<td>Fuse (1)</td>
<td>A21 020400</td>
<td>2</td>
<td>3.15A SLOW for 110VAC</td>
</tr>
<tr>
<td>Fuse (2)</td>
<td>A21 018300</td>
<td>2</td>
<td>1.6A SLOW for 240VAC</td>
</tr>
</tbody>
</table>

1.5 Optional Accessory

<table>
<thead>
<tr>
<th>Item</th>
<th>Part Number</th>
<th>Q’ty</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>RJ-45 twin head link cable</td>
<td>W39 000695</td>
<td>1</td>
<td>L: 450mm</td>
</tr>
<tr>
<td>RJ-45 twin head link cable</td>
<td>W38 029300</td>
<td>1</td>
<td>L: 1000mm</td>
</tr>
<tr>
<td>RJ-45 twin head link cable</td>
<td>W39 000694</td>
<td>1</td>
<td>L: 2000mm</td>
</tr>
<tr>
<td>RJ-45 twin head link cable</td>
<td>W38 029200</td>
<td>1</td>
<td>L: 4000mm</td>
</tr>
<tr>
<td>DB-9F single head link cable</td>
<td>W39 000771</td>
<td>1</td>
<td>L: 7000mm</td>
</tr>
<tr>
<td>Across HV head + HV cable</td>
<td>W25 000045</td>
<td>1</td>
<td>L: 2000mm</td>
</tr>
<tr>
<td>Black banana head + HV cable</td>
<td>W25 000046</td>
<td>1</td>
<td>L: 2000mm</td>
</tr>
</tbody>
</table>

Remark: Optional accessory is for link test model of 19073 + RS485 only.
2. Operation and Setting

2.1 Front Panel

The front panel is divided into several function areas. This section explains each control and the information displays on LCD.

### Button Area
- **Stop Button**

### Display Area
- **Power Switch**
- **Status Line**
- **Pass Indicator**
- **Test Status Indicator**
- **Common Test Terminal**
- **High Voltage Output Terminal**

### Function Key Display Area
- **Function Keys**

#### 2.1.1 Display Area

- **Function Key Display Area:** Different function text appears in different menu. The mapping function keys (F1-F4) are located at right. The function key is invalid if the text is blank.

- **Status Line:** This line shows the setting mode, value range, and test results.

- **RMT:** When the text is highlighted, it means the system is under on-line status.

- **LOCK:** When the text is highlighted, it means the system is under protection via parameter.

- **OFST:** When the text is highlighted, it means the leakage current has been offset by the system.
ERR: When the text is highlighted, it means the system transmission is error.

Test State Indicator: The DANGER indicator, when it lights up it indicates the instrument is under test condition and there is high voltage or mass current output on the test terminal. Do not touch the test terminal at this time.

Pass Indicator: When it lights up it indicates the DUT passes the test. This indicator remains lit up until [STOP] is pressed.

Fail Indicator: When it lights up it indicates the DUT fails the test. This indicator remains lit up until [STOP] is pressed.

2.1.2 Button Area

Power Switch: The switch to supply the AC power source for this instrument.

Stop Button [STOP]: Press this button the instrument will return to the ready state for testing and cut out output as well as clear all judgments.

Start Button [START]: Press this button the instrument will be in test state, which means there are outputs at the test terminal and all judgment functions are activated.

Calibration Switch: It is used by Chroma for calibration before shipping the product. Nonprofessional is prohibited to use this function to avoid causing any damage.

Function Keys: There are different functions in different display menus. The mapping function description text is at right of the menu. The function key is invalid if the description text is blank.

2.1.3 Terminal Area

High Voltage Output Terminal: The terminal of high voltage with high potential is located at high potential terminal for high voltage output. This test terminal is very dangerous especially when the DANGER indicator is lit up. Do not touch it when there is high voltage output.

Common Test Terminal (RET/LOW): It is the reference terminal at high voltage test, i.e. the low potential terminal almost equals to the chassis grounding.
2.2 Rear Panel

The rear panel is divided into several areas. This section describes the function of each area.

The standard rear panel of 19071/19072/19073:

The rear panel of link test model of 19073 + RS485 is shown as below:
(1) REMOTE CONTROL

- The connection diagram of remote control signals is as the following.

![Connection Diagram]

- START: The input terminal for start test signal.
- RESET: The input terminal for stop test signal.
- COM: The common input terminal for START and RESET signal.
- UNDER TEST: This terminal will short-circuit when in test mode, thus it can be used to control the external signal. The connecting point specification is 115V AC, current less than 0.3A. The action time is from the instrument enters the test mode until it is reset or completes the test.
- PASS: This terminal will short-circuit when the DUT passes the tests, thus it can be used to control the external signal. The connecting point specification is 115V AC, current less than 0.3A. The action time is from the DUT is passed until it is reset.
- FAIL: This terminal will short-circuit when the DUT fails the tests, thus it can be used to control the external signal. The connecting point specification is 115V AC, current less than 0.3A. The action time is from the DUT is failed until it is reset.

(2) VOLTAGE SELECTOR: Input Power Range Switch

- To change the input AC power source for the following 4 types:
  - Voltage range 90V ~ 110V AC (3.15AT, 250V)
  - Voltage range 108V ~ 132V AC (3.15AT, 250V)
  - Voltage range 198V ~ 242V AC (1.6AT, 250V)
  - Voltage range 216V ~ 250V AC (1.6AT, 250V)

- Be sure to use correct fuse when switch the power source.

(3) AC LINE: AC Power Socket and Fuse Holder

It is a three-pin power socket and a fuse holder. AC power is inputted from this socket to supply the AC source needed by this instrument. For detailed usage and specification of fuse, see Chapter 3 Installation and Maintenance.
(4) **EARTH GROUND TERMINAL: Terminal Grounding for Safety**
   Use appropriate tools to ground this terminal surely. If it is not grounded surely, when the power circuit or any other devices connection short-circuited with the ground terminal, the instrument chassis may contain high voltage. This is very dangerous as it may cause electric shock if anyone touches it under the situation; therefore, it is necessary to connect the ground terminal to earth assuredly.

(5) **CONTINUITY CHECK: Ground continue measuring and current output terminal**
   This function is for detecting ground continues of DUT grounding terminal.

(6) **FAN**
   The fan is activated simultaneously when the tester is powered on.

(7) **Expanded Slot**
   The standard is 5PIN terminal slot, this slot provides the following functions:
   - The connection diagram of expanded slot signals is as the following.

   ![Connection Diagram]

   - START: Input terminal of starting test signal.
   - RESET: Input terminal of stopping test signal.
   - COM : Input common terminal of START and RESET signals.
   - INTER LOCK: Short-circuited these two terminals, then can output high voltage. (This function is only for installing 5PIN on expanded slot. If this unit is link test model of 19073 + RS485, these two terminals are short-circuited fixedly.)

(8) **HV OUTPUT Terminal**
   This terminal is the same as HV output terminal of front panel.

(9) **Common Test Terminal: RET/LOW**
   This terminal is the same as common test terminal of front panel.

(10) **Expanded Slot**
    This slot supports two sockets of RJ-45, which provides multi-link function for the link test model of 19073 + RS485.
2.3 Operation

[Standby Menu]: The screen appears as below after powered on.

<table>
<thead>
<tr>
<th>STEP 1/ 1 AC</th>
<th>LOW :OFF</th>
<th>PROGRAM</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.000KV</td>
<td>ARC :OFF</td>
<td>PRESET</td>
</tr>
<tr>
<td>0.500mA</td>
<td>RAMP:OFF</td>
<td>MENU</td>
</tr>
<tr>
<td>3.0s</td>
<td>FALL:OFF</td>
<td>MORE..</td>
</tr>
</tbody>
</table>

2.3.1 Memory Process

- How to enter the Memory Process menu

  1. In [Standby Menu], press the Function Key [MENU], it appears:

     | 1. MEMORY | 2. SYSTEM | 3. OPTION | 4. CALIBRATION | 5. KEY LOCK |
     | SELECT FUNC. | RMT | LOCK | OFST | ERR |
     | LAST | DOWN | SELECT | EXIT |

  2. Use Function Key [F1] and [F2] to move the highlight to “MEMORY”, and press Function Key [F3] to enter memory process menu as below:

     | 1. (0 STEPS) | 2. (0 STEPS) | 3. (0 STEPS) | 4. (0 STEPS) | 5. (0 STEPS) |
     | STORE | RECALL | DELETE | RETURN |
     | SELECT FUNC. | RMT | LOCK | OFST | ERR |

  3. At this time select execution action by pressed Function Key [F1], [F2] or [F3], it appears:

     | 1. (0 STEPS) | 2. (0 STEPS) | 3. (0 STEPS) | 4. (0 STEPS) | 5. (0 STEPS) |
     | LAST | DOWN | SELECT | RETURN |
     | SEL. MEMORY | RMT | LOCK | OFST | ERR |
(4) At this time use Function Key [F1] and [F2] to move the highlight to the memory for processing, then press Function Key [F3] will prompt a confirmation window. Press Function Key [ENTER] to confirm and Function Key [UP] or [DOWN] to select stored character of file name. Press [NEXT.C] to select next character and [ENTER] to confirm the file name, the maximum file name is 10 characters.

(5) When executing [RECALL] or [DELETE] function, use Function Key [F1] and [F2] to move the highlight to the memory for processing, then press Function Key [F3] will prompt a confirmation window. Press Function Key [YES] to confirm or Function Key [NO] to cancel, then can recall or delete the memory set. Each memory contains test parameters, preset parameters and number of test steps.

2.3.2 System Setup

How to enter the SYSTEM SETUP menu
(1) In [Standby Menu], press the Function Key [MENU] and by using Function Key [F1], [F2] to move the highlight to “SYSTEM” and then press Function Key [F3] to enter into the parameter setting menu as below:

(2) Use Function Key [F3] to move the highlight to the parameter item you want to set, then use Function Key [F1] and [F2] to set the parameter data.
(3) System Parameter Setting Table

<table>
<thead>
<tr>
<th>Item</th>
<th>Range</th>
<th>Default</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CONTRAST</td>
<td>1~15</td>
<td>7</td>
<td>Adjust the LCD brightness</td>
</tr>
<tr>
<td>BUZZER VOLUME</td>
<td>HIGH/MEDIUM /LOW/OFF</td>
<td>HIGH</td>
<td>Adjust the buzzer volume</td>
</tr>
<tr>
<td>EN50191</td>
<td>ON/OFF</td>
<td>OFF</td>
<td>The output is meet to EN50191 requirement (AC Max 3mA, DC Max 5mA)</td>
</tr>
<tr>
<td>DC 50V AGC</td>
<td>ON/OFF</td>
<td>OFF</td>
<td>Select if open hardware AGC as DC voltage setting is 50V~499V. (When this item is OFF, hardware AGC is opened only DC voltage set to above 500V automatically.)</td>
</tr>
</tbody>
</table>

2.3.3 PRESET Parameter Setting

- How to enter the PRESET menu

In [Standby Menu], press Function Key [PRESET] to enter the PRESET menu as shown below:

```
1. ACV FREQUENCY: 60Hz UP
2. SOFTWARE AGC : ON
3. WV AUTO-RANGE: OFF DOWN
4. IR AUTO-RANGE: ON NEXT
5. GFI            : ON EXIT

50Hz/60Hz RMT LOCK OFST ERR
```

(1) After entering the PRESET parameter setting menu, press Function Key [F3] to move the highlight to the parameter item you desired to set.
(2) Press Function Key [F1] and [F2] to set the parameter data.
(3) PRESET parameter function table as shown below:

<table>
<thead>
<tr>
<th>Item</th>
<th>Range</th>
<th>Default</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACV FREQUENCY</td>
<td>50 / 60 Hz</td>
<td>60Hz</td>
<td>Set the output voltage frequency at AC HiPot test.</td>
</tr>
<tr>
<td>SOFTWARE AGC</td>
<td>OFF / ON</td>
<td>ON</td>
<td>Set if open the software AGC function.</td>
</tr>
<tr>
<td>WV AUTO-RANGE</td>
<td>OFF / ON</td>
<td>OFF</td>
<td>Set if open the HiPot auto range function.</td>
</tr>
<tr>
<td>IR AUTO-RANGE</td>
<td>OFF / ON</td>
<td>ON</td>
<td>Set if open the insulation auto range function.</td>
</tr>
<tr>
<td>GFI</td>
<td>OFF / ON</td>
<td>ON</td>
<td>Set if open the GFI function.</td>
</tr>
<tr>
<td>FAIL RESTART</td>
<td>OFF / ON</td>
<td>OFF</td>
<td>Set if restart directly when fails the test.</td>
</tr>
</tbody>
</table>
2.3.4 PROGRAM Parameter Setting

- **Test parameter setting**
  
  (1) In [Standby Menu], press Function Key [PROGRAM] to enter the PROGRAM setting menu as the following:

<table>
<thead>
<tr>
<th>STEP</th>
<th>AC</th>
<th>LOW : OFF</th>
<th>NEW</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>ARCH : OFF</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>VOLT : 0.050kV</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>RAMP : OFF</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>HIGH : 0.500mA</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>FALL : OFF</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>TIME : 3.0s</td>
<td></td>
</tr>
</tbody>
</table>

  - 1-10 | RMT | LOCK | OFST | ERR | EXIT |

- **Test steps setting**
  
  (1) Press [F3] to move the highlight and stay in the test item. When Function Key [F1] shows “UP”, it means press this key can switch to the next test step. When Function Key [F1] shows “NEW”, it means press this key can add a test step. When Function Key [F1] shows “FIRST”, it means press this key can switch the first test step.

  (2) Use Function Key [F2] can switch the functions as shown below:

<table>
<thead>
<tr>
<th>STEP</th>
<th>AC</th>
<th>LOW : OFF</th>
<th>DELETE</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>ARCH : OFF</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>VOLT : 0.500kV</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>RAMP : OFF</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>HIGH : 0.500mA</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>FALL : OFF</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>TIME : 3.0s</td>
<td></td>
</tr>
</tbody>
</table>

  - VOLTAGE IS 0 | RMT | LOCK | OFST | ERROR | RETURN |

  (3) Function Key [DELETE] to delete a selected test step.

  (4) Function Key [INSERT] to insert a new test step set.

  (5) Function Key [DOWN] to select to previous test step set.

- **Selecting Test Mode**

  Press Function Key [F3] to move the highlight and stay in the test item. Use Function Key [F1] and [F2] to select the test mode. There are AC/GC/PA, AC/DC/PA and AC/DC/IR/GC/PA test modes for selection by different model. Different test mode has different test parameters for setting.

- **Description of each test parameter setting**: The following explain the parameter setting of each test mode.
(1) AC HiPot Test Mode

<table>
<thead>
<tr>
<th>STEP 1/1 AC LOW : OFF UP</th>
</tr>
</thead>
<tbody>
<tr>
<td>ARC : OFF</td>
</tr>
<tr>
<td>VOLT: 0.000kV RAMP: OFF</td>
</tr>
<tr>
<td>HIGH: 0.500mA FALL: OFF</td>
</tr>
<tr>
<td>TIME: 3.0s</td>
</tr>
</tbody>
</table>

SELECT MODE RMT LOCK OFST ERR EXIT

VOLT : Set the required voltage for HiPot test.
HIGH : Set the upper limit for leakage current.
TIME : Set the required time for testing, 0 means continuous test. (Judge the high and low limit for leakage current during the time.) The voltage value is shown which within specification, the minimum test time should be equal to 0.3 second. When the displayed voltage is not reach to 9/10(Software AGC ON) or 2/3(Software AGC OFF) of setting voltage value, the judgment function will show FAIL.
LOW : Set the low limit for leakage current, 0 means OFF.
ARC : Set the high limit for ARC, 0 means OFF.
RAMP : Set the required time for rising to selected voltage, 0 means OFF.
FALL : Set the required time for falling from selected voltage to zero, 0 means OFF.

(2) DC HiPot Test Mode

<table>
<thead>
<tr>
<th>STEP 1/1 DC LOW : OFF UP</th>
</tr>
</thead>
<tbody>
<tr>
<td>ARC : OFF</td>
</tr>
<tr>
<td>VOLT: 0.000kV RAMP: OFF</td>
</tr>
<tr>
<td>HIGH: 0.500mA DWELL: OFF</td>
</tr>
<tr>
<td>TIME: 3.0s FALL : OFF</td>
</tr>
<tr>
<td>I-RUS: OFF</td>
</tr>
</tbody>
</table>

SELECT MODE RMT LOCK OFST ERR EXIT

VOLT : Set the required voltage for HiPot test.
HIGH : Set the high limit for leakage current.
TIME : Set the required time for testing, 0 means continuous test. (Judge the high and low limit for leakage current during the time.) The voltage value is shown which within specification, the minimum test time should be equal to 0.2 second. When the displayed voltage is not reach to 9/10(Software AGC ON) or 2/3(Software AGC OFF) of setting voltage value, the judgment function will show FAIL.
LOW : Set the low limit for leakage current with the value less than the high limit for leakage current or OFF.
ARC : Set the high limit for ARC, 0 means OFF.
RAMP : Set the required time for rising to selected voltage, 0 means OFF.
DWELL : Set DWELL time, 0 means OFF. (Do not judge the high and low limit for leakage current during DWELL TIME operation, but do not over the high limit of setting range.)
FALL : Set the required time for falling from selected voltage to zero, 0 means OFF.
I-RUS : Set the low limit for inrush current, 0 means OFF.
**Operation and Setting**

### (3) Insulation Resistance Test Mode

<table>
<thead>
<tr>
<th>STEP 1/1 IR</th>
<th>HIGH: OFF</th>
<th>RAMP: OFF</th>
<th>UP</th>
</tr>
</thead>
<tbody>
<tr>
<td>VOLT: 0.000kV</td>
<td>DWELL: OFF</td>
<td>DOWN</td>
<td></td>
</tr>
<tr>
<td>LOW: 1.0MΩ</td>
<td>FALL: OFF</td>
<td></td>
<td></td>
</tr>
<tr>
<td>TIME: 3.0s</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- **VOLT**: Set the required voltage for insulation resistance test.
- **LOW**: Set the low limit for insulation resistance.
- **TIME**: Set the time required for test, 0 means continuous test. (Judge the high and low limit for insulation resistance during the time.)
- **HIGH**: Set the high limit for insulation resistance with the value larger than the low limit of insulation resistance or OFF.
- **DWELL**: Set the required time for test, 0 means OFF. (Do not judge the high and low limit for insulation resistance during this period.)
- **FALL**: Set the required time for falling from selected voltage to zero, 0 means OFF.

### (4) Ground Continue Mode

<table>
<thead>
<tr>
<th>STEP 1/1 GC</th>
<th>LOW: OFF</th>
<th>UP</th>
</tr>
</thead>
<tbody>
<tr>
<td>CURR: 0.0A</td>
<td>HIGH: 1.0Ω</td>
<td>DOWN</td>
</tr>
<tr>
<td>DWELL: 0.3s</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- **CURR**: Set the output current (0.1A maximum).
- **HIGH**: Set the high limit of ground continue (0.1Ω ~ 5Ω).
- **DWELL**: Set the time required for test (0.1 sec ~ 1 sec). (Do not judge the high and low limit for ground continue during the time.)
- **LOW**: Set the low limit for ground continue with the value lower than the high limit of ground continue or OFF.

### (5) Pause Mode

<table>
<thead>
<tr>
<th>STEP 1/1 PA</th>
<th>PAUSE:PAUSE MODE</th>
<th>UNDER TEST SIGNAL:OFF</th>
<th>UP</th>
</tr>
</thead>
</table>

- **PAUSE**: Set the signal shown on menu when pause, the maximum length is 15 characters.
- **UNDER TEST SIGNAL**: Set UNDER TEST signal on the rear panel and DANGER indicator on the front panel when pause.
2.4 How to Perform Tests

- **Test Cable Offset Calibration**
  
  (1) In [Standby Menu], press Function Key [MORE..] to enter the test menu of multiple STEPS.
  
  (2) Press Function Key [OFFSET], the monitor will show a menu to indicate you to open the output terminal.
  
  (3) Press [START], the DANGER indicator on the front panel will light up. The test time is 5 seconds. The system starts to measure the test cable offset and shows the reading on monitor, then saves it to memory.

- **Connection the DUT**
  
  First, ensure there is no voltage output and the DANGER indicator is off. Then connect the low potential test cable (black) to the common test terminal on system, and secure it with fixed plate. Short-circuit the test cable and high voltage output terminal. After confirming no high voltage is output, connect the DUT with low potential test cable first and high potential test cable later, and then plug in the high voltage test cable (red or white) to “High Voltage Output Terminal”.

- **Test Steps**
  
  (1) Connection the DUT with correct procedures.
  
  (2) In [Standby Menu] (as shown below):

  ![Standby Menu Diagram]

  1. STEP 1/2 in “Line 1” indicates there are 2 test steps, and currently it is executing step 1. M02 1/2 in “Line 1” indicates this test parameter set have saved into the index 2 memory. There are 2 test steps in the memory, and currently it is executing step 1.

  2. AC in “Line 1” indicates this step is AC HiPot test mode.

  3. “Line 2” indicates the output voltage set for test.

  4. “Line 3” indicates the high limit for leakage current under STANDBY state in AC or DC HiPot test mode; or the low limit for insulation resistance under STANDBY state in IR test mode. When in TEST mode, it is the value of real leakage current or insulation resistance.
5. “Line 4” indicates the testing time set under STANDBY state; or the remaining testing time under TEST state.
6. “Line 5” is the “Status Line” that shows the current state or test results.

(3) Press [STOP] to enable it standby for test and the “Status Line” shows “STANDBY”.

(4) Press [START] to begin the test. It will begin to output the test voltage. The DANGER indicator lights up and the “Status Line” shows “UNDER TEST” to warn you that it is in test state and there is mass voltage output. “Line 2” will show the output voltage reading, “Line 3” will show the reading of leakage current or insulation resistance, and “Line 4” performs timing and countdown work.

(5) PASS Judgment
When all test steps are done and “Status Line” shows PASS, it indicates the DUT is a quality product. Then the output is cut out, rear panel outputs the PASS signal and buzzer (short beep) in the meantime.

(6) FAIL Judgment
If the measurement is abnormal, the system will judge the DUT as a failed product and cut out the output. The rear panel outputs FAIL signal and buzzer (long beep) in the meantime. The action continues until [STOP] key is pressed. “Status Line” will show fail state as below.

<table>
<thead>
<tr>
<th>Test Result</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>PASS</td>
<td>Passed the tests judge as PASS product</td>
</tr>
<tr>
<td>HIGH FAIL</td>
<td>Measurement is over the high limit</td>
</tr>
<tr>
<td>LOW FAIL</td>
<td>Measurement is under the low limit</td>
</tr>
<tr>
<td>ARC FAIL</td>
<td>Current ARC is over the high limit</td>
</tr>
<tr>
<td>I/O FAIL</td>
<td>Hardware detects bad signal</td>
</tr>
<tr>
<td>NO OUTPUT</td>
<td>Output is not enough (Maybe the test time is not enough)</td>
</tr>
<tr>
<td>VOLT OVER</td>
<td>Voltage reading is over the hardware valid digits</td>
</tr>
<tr>
<td>CURR OVER</td>
<td>Current reading is over the hardware valid digits</td>
</tr>
<tr>
<td>INRUSH FAIL</td>
<td>Charging current is over low (Test fixture bad contact)</td>
</tr>
<tr>
<td>GFI TRIPED</td>
<td>Grounding failed interrupted</td>
</tr>
</tbody>
</table>

(7) If any errors happen and cause the [START] key to be locked, you can press [STOP] to release it.

(8) You can press [STOP] key anytime to stop the test output in any case.
2.5 Other User Setting Function

2.5.1 KEY LOCK Function

Setting KEY LOCK

In [Standby Menu], you can enable KEY LOCK function if [LOCK] is not highlighted.

1. Press Function Key [MENU], use Function Key [F1] and [F2] to move the highlight to “KEY LOCK”, and press Function Key [SELECT] to enter into the KEY LOCK setting menu.

```
KEY LOCK
USER PASSWORD:****
ENTER
1-10 CHAR. RMT LOCK OFST ERR RETURN
```

2. Use Function Key [A] and [B] to input the PASSWORD (default is AAAA.)

3. Press Function Key [ENTER] will prompt a selection window is highlighted.

```
KEY LOCK ON !
RECALL LOCK ?
YES NO
1-10 CHAR. RMT LOCK OFST ERR CANCEL
```

4. You can press Function Key [YES] or [NO] to select if lock the MEMORY RECALL function as well. Exit the menu after completing KEY LOCK function and [LOCK] is highlighted in the meantime.

5. Press Function Key [CANCEL] to cancel the action and exit the set menu.

Canceling KEY LOCK

In [Standby Menu], you can release KEY LOCK if [LOCK] is highlighted. Follow the steps above to cancel KEY LOCK, and [LOCK] will not be highlighted.
2.5.2 Auto Range

(1) Set WV-AUTO RANGE as ON under PRESET function list.
(2) The current set to high range as below shown.

<table>
<thead>
<tr>
<th>STEP 1/1 AC</th>
<th>LOW: OFF</th>
<th>PROGRAM</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.050kV</td>
<td></td>
<td></td>
</tr>
<tr>
<td>20.00mA</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3.0s</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(3) The test is ended before 0.6 sec, if the current is shown as low range then the current auto range to low range as the following figure.

<table>
<thead>
<tr>
<th>STEP 1/1 AC</th>
<th>LOW: OFF</th>
<th>PROGRAM</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.050kV</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0.100mA</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0.0s</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

2.5.3 Change User Password

(1) In [Standby Menu], press Function Key [MENU], and use Function Key [F1] and [F2] to move the highlight to “CHANGE PASSWORD” and press Function Key [SELECT] to enter into the password menu.

<table>
<thead>
<tr>
<th>CHANGE PASSWORD</th>
</tr>
</thead>
<tbody>
<tr>
<td>USER PASSWORD:****</td>
</tr>
</tbody>
</table>

(2) Use Function Key [A] and [B] to input the original PASSWORD (default is AAAA), and press Function Key [ENTER] will show the following “NEW PASSWORD” window.
(3) Use Function Key [A] and [B] to input the NEW PASSWORD (maximum 10 characters), and press Function Key [ENTER] will display the “CONFIRM” window.

(4) Use Function Key [A] and [B] to input the NEW PASSWORD, and press Function Key [ENTER]. Press [RETURN] after completing the setting.

### 2.5.4 Remote Control

- **Be aware** when using remote control by external signal and do not touch the high voltage terminal to avoid causing any danger.

- The REMOTE outlet for remote control switch is located at the rear panel. You can plug in the control line to use external signal for controlling the device output externally.

- Remote control is usually done by high voltage testing bar; however, you can also use other control circuit to do it. Be careful that it is the switch to control high voltage output, so you must connect the control line with caution and do not get near the high voltage terminal and test cable to avoid causing any danger.

- For single control of START and RESET signals follow Figure 1 listed below to connect them to the REMOTE position on the system back panel.

- If it is connected as Figure 2 shows, the system routine is in RESET state as the NC is connected to RESET and NO is connected to START.
The logic components of transistor, FET and couplers can be connected and used as control circuit. The connected signals and circuit are shown as below. To use this circuit to control the system, it must contain the following:

1. The current of LOW signal is 2mA or less.
2. The active time for input signal is more than 20mS.

Either the relay switch control in Figure 1 or the coupler control in Figure 3 uses the contact of components for control action. It can prevent the error operation from interference effectively. Though the system has a lot of precautions, you would still need to watch out the interference caused by the measurement system settings.

### 2.5.5 Output Signal

This instrument has indicator and beeper for indication signals. The output signals in the system rear panel are:

- **UNDER TEST**: This terminal will short-circuit when in test mode, thus it can be used to control the external signal. The connecting point specification is 115V AC, current less than 0.3A.

- **PASS**: This terminal will short-circuit when the DUT passes the tests, thus it can be used
to control the external signal. The connecting point specification is 115V AC, current less than 0.3A. The action time is from the DUT is passed until it is stopped.

- **FAIL**: This terminal will short-circuit when the DUT fails the tests, thus it can be used to control the external signal. The connecting point specification is 115V AC, current less than 0.3A. The action time is from the DUT is failed until it is stopped.
3. Installation and Maintenance

3.1 Notices for Installation

This instrument generates high voltage output up to 6KV for external test. Any incorrect or mistaken procedures in using this instrument may cause injury or death. Thus for your safety, be sure to read through the notices described in this chapter and memorize them to prevent any accidents from happening.

- Induction and electric shock
  To avoid electric shock, we suggest you to put on the insulation rubber gloves before performing any electricity related work.

- Grounding
  There is a safety grounding terminal at the instrument rear panel. Ensure to use appropriate tools to connect the grounding terminal surely. If it is not grounding correctly, the chassis of test machine may contain high voltage when the power circuit or the connecting line of any devices short-circuited with the grounding terminal. This is very dangerous as it may cause electric shock if anyone touches the instrument under the circumstances. Therefore, it is necessary to connect the safety grounding terminal to earth correctly. See 2.2 Rear Panel Description for detail information.

- Connecting test cable to the “Common Test Terminal”
  Please connect the test cable to “Common Test Terminal” actually. Always check if the test cable is connected properly during test. When you need to connect the test cable to the unit for test, use the one on Common Test Terminal first to connect the DUT. It is very dangerous if the test cable on Common Test Terminal is not connected completely or loose as the entire DUT may contain high voltage. Refer to 2.1 Front Panel Description.

- Connecting test cable to the “High Voltage Output Terminal”
  Follow the procedures below to connect the high voltage output line after the “Common Test Terminal” is connected.
  - Press [STOP] button first.
  - Ensure the DANGER indicator is off.
  - Short circuit the “Common Test Terminal” test cable and “High Voltage Output Terminal”, and ensure there is no voltage output.
  - Last, connect the “Common Test Terminal” test line to the DUT and then the high voltage test cable to the DUT.
  - Plug in the high voltage test cable to the “High Voltage Output Terminal”.

- End test
  When tests are done and the test instrument is not in use or need to leave for a while during usage, make sure to turn off the power switch (to O). See 2-1 Front Panel Description for detail information.

- Dangerous places when the instrument is in test mode
  It is very dangerous to touch the area with high voltage such as the DUT, test cable,
probe, and output terminal when the instrument is in test mode.

× DO NOT touch the alligator clip as shown below on the test cable when the system is in test mode as the rubber insulation is not good enough and may cause danger if touched.

End test confirmation
You may touch the DUT, high voltage test cable or high voltage output area like output terminal in order to alter the layout or perform particular test request, thus be sure to turn off the power before doing it. For testing the DC HiPot/insulation resistance, the DUT may contain high voltage after completing the test, so you need to carefully follow the instructions described in this chapter to perform the work.

3.1.1 Charging During DC HiPot/Insulation Resistance Test

Charge
When doing DC HiPot/insulation resistance test, the DUT, capacitor, test cable, probe and output terminal, even the test instrument may charge with high voltage. The charged voltage may need a period of to discharge after the power switch is turned off. Do not touch any places that may cause electric shock as mentioned above especially at the moment of turning off the power.

Confirming the charged voltage is discharged totally
the test voltage applied as well as the DUT characteristics determines the total discharge time for the charged voltage. Assuming the high voltage on the DUT is the voltage plus a 0.01uF capacitor paralleling a 100MΩ resistance circuit, then after turning off the power the voltage on test instrument and DUT takes about 3.5 seconds to decrease to 30V. Thus when the test voltage is 500V, it needs about 2.8 seconds. Suppose we already know the time constant of a DUT, you can follow the description above to calculate the time required for voltage decreasing to beneath 30V after turning off the power. The method is using the time decreased to under 30V multiplies the time constant ratio as the figure shown below.
<Formula>
Test Voltage * e^{\frac{-t}{RC}} = Residual Voltage

Ex.: 1000V * e^{\frac{-t}{RC}} = 30V
\ln e^{\frac{-t}{RC}} = \ln 0.03
- \frac{t}{RC} = -3.5
\therefore t = 3.5 sec

Remote control system
This system is capable of remote control. Usually it uses external control signal to do the high voltage output control. For your safety and to prevent accidents, the following principles of control must be performed accurately. Do not allow any unexpected high voltage output to cause any hazards. When the system has high voltage output, operators and other personnel are not allowed to touch the DUT, test cable and probe and output terminal, etc.

Turn the power switch on or off
Attention
Once the power switch is cut off, wait a few seconds to turn it on again. Do not turn on/off the power switch repeatedly to avoid causing any errors. It is very dangerous to do repeating power on/off in high voltage output state.
The high voltage output terminal cannot connect to any objects during power on or off to avoid hazards caused by abnormal high voltage output.

Miscellaneous notices
Do not short circuit the instrument output line, grounding line, transmission line, or other connector grounding line, and AC source to avoid the entire test device being charged to a very dangerous voltage. To short circuit the High Voltage Output Terminal and Common Test Terminal, the instrument chassis must be grounded to earth first.

3.1.2 Emergency Events

Emergency management
In the emergency situations of electric shock, DUT on fire or system on fire, follow the steps below to avoid causing bigger hazards.
\[\square\] First, cut off the power switch.
\[\square\] Then, unplug the power cord.

3.1.3 Solving Problems

When problem happens
The problems in the following conditions are very dangerous. The output terminal may still have high voltage output even the [STOP] button is pressed, so you need to be very careful.
\[\square\] The DANGER indicator still lights up after the [STOP] button is pressed.
\[\square\] There is no reading on voltage meter, however the DANGER indicator is lit.
When any of the above conditions happens, turn off the power and unplug the AC
power cord. Do not use it again as the failure is very dangerous. Send it back Chroma or dealer for repair and services.

DANGER indicator failure
If you press the [START] button and the voltage meter shows readings but the DANGER indicator is still off, it means the indicator may be failure. Turn the instrument off and replace it immediately, then return the malfunction device to Chroma or dealer for repair and services.

Notices when operating the instrument of long duration under normal condition
If the setting high limit closes to the rated value, pay attention to the temperature changes. Stop using it if the ambient temperature is over 40°C. Wait until the temperature is down to normal to resume the operation, and the instrument must be inspected first.

There are four types of AC INPUT power source used in this instrument
Switch the voltage selector on the rear panel to the correct position according to the voltage used locally. Ensure the AC power source is same as marked on the power switch that located on the rear panel, and the fuse is changed to the appropriate one when plug in the power cord. Following table lists the fuses for the voltage used:

<table>
<thead>
<tr>
<th>Center Voltage</th>
<th>Range</th>
<th>Fuse</th>
</tr>
</thead>
<tbody>
<tr>
<td>100V</td>
<td>90V ~ 110V</td>
<td>3.15A Slow/250V</td>
</tr>
<tr>
<td>120V</td>
<td>108V ~ 132V</td>
<td>3.15A Slow/250V</td>
</tr>
<tr>
<td>220V</td>
<td>198V ~ 242V</td>
<td>1.6A Slow/250V</td>
</tr>
<tr>
<td>240V</td>
<td>216V ~ 250V</td>
<td>1.6A Slow/250V</td>
</tr>
</tbody>
</table>

The fuse should conform to the voltage used and replace it when the power cord is unplugged to avoid electric shock. When replacing the fuse, press the fuse holder inside the power socket then remove the existing fuse and insert the new one, then plug in the power cord.

Caution
Be sure to use correct fuse when changing it, or it may cause danger easily.

This instrument operates in AC power source.
If the power source is unstable in the range selected, it may cause the instrument to act abnormally or inaccurately. Please use appropriate equipment such as power regulator to convert it to applicable power source.

This instrument uses the power transformer 200VA or above.
If the tested device draws a great amount of current, it may flow in large current (about 10 Ampere) up to 10mS before the judgment of fail and output current cut off. The same situation may occur before performing the test. Thus it is necessary to pay attention to the capacity of power cord and the current line linked with other instruments and devices.

Storage
The normal temperature range is 18°C~28°C, ≤ 70% RH. The operation may incorrect
if over the range. The storage temperature is -10°C~60°C, ≤ 80% RH. If you are not planning to use it for a long period of time, pack it with the original box for storage. For the sake of correct test and safety of this instrument, make sure not to store it in a place with direct sunlight or high temperature, also away from shaky, damp and dusty area.

- **Warming up**
  This instrument activates at power on; however, in order to meet the accuracy specified in the specification, please warm it up for 15 minutes or above.

- **Safety Symbols**

  - ![Warning Symbol] : It indicates the output terminal may contain lethal voltage. Read all safety operation notices carefully.
  
  - ![Attention Symbol] : It indicates to read the detailed descriptions in the user’s manual.
  
  - ![Grounding Symbol] : It indicates the grounding protect terminal, which is used to prevent electric shock from the leakage on chassis. The ground terminal must connect to earth before using the product.

- **Warning**
  This is to warn user to avoid the product misuse due to procedures, applications or other reasons. It may cause hazard to human if the warning is neglected.

- **Caution**
  This indicates the caution to user to avoid the product misuse due to procedures, applications or other reasons. It may cause unexpected result to the product itself and the DUT if the caution is neglected.

- **Note**
  This indicates important information or tips for the procedures and applications, etc. The contents should be read carefully.

- **Warning Signal of Testing**
  “DANGER – HIGH VOLTAGE TEST IN PROGRESS, UNAUTHORIZED PERSON KEEP AWAY”

### 3.2 Notices for Maintenance

Except notified in the manual there is no items can be maintained by user in this device.

Please contact Chroma or sales agent when any abnormal condition occurs in this device. Do not perform maintenance by yourself to avoid causing any unnecessary hazards that may damage the device.
3.3 Troubleshooting

Besides replacing the fuse (see 3.1.3 Solving Problems) or other notified in the manual, there is no troubleshooting to be performed by user.

Please contact Chroma or sales agent when any abnormal condition occurs in this device. Do not perform maintenance by yourself to avoid causing any unnecessary hazards that may damage the device.

3.4 Input/Output Pin Assignment

See the descriptions of front panel and rear panel in Chapter 2.
4. Calibration Procedure

Before performing this section the HiPot tester must warm up at least for 30 minutes.
Take off the calibration label at the front panel and press the lock switch. After completed the calibration, please press the lock switch again for opening the hardware data backup protection circuit to avoid calibration data loss.

The following items are required for calibration.

- **Voltage Calibration (See 4.2)**
  - ACV 5KV Offset (0.05kV): AC HiPot Voltage Offset calibration (AC Mode)
  - ACV 5KV Full (4KV): AC HiPot Voltage Full calibration (AC Mode)
  - DCV 6KV Offset (0.05kV): DC HiPot Voltage Offset calibration (DC/IR Mode)
  - DCV 6KV Full (4KV): DC HiPot Voltage Full calibration (DC/IR Mode)
  - IRV 1KV Offset (0.05kV): IR Impedance Voltage Offset calibration (DC/IR Mode)
  - IRV 1KV Full (1kV): IR Impedance Voltage Full calibration (DC/IR Mode)

- **Current Calibration (See 4.3)**
  - ACA 3mA Offset (0.12mA): AC HiPot current 3mA range Offset calibration (AC Mode)
  - ACA 3mA Full (2.4mA): AC HiPot current 3mA range Full calibration (AC Mode)
  - ACA 20mA Offset (2.4mA): AC HiPot current 20mA range Offset calibration (AC Mode)
  - ACA 20mA Full (12mA): AC HiPot current 20mA range Full calibration (AC Mode)
  - DCA 3mA Offset (0.12mA): DC HiPot current 3mA range Offset calibration (DC/IR Mode)
  - DCA 3mA Full (2.4mA): DC HiPot current 3mA range Full calibration (DC/IR Mode)
  - DCA 5mA Offset (2.4mA): DC HiPot current 5mA range Offset calibration (DC/IR Mode)
  - DCA 5mA Full (4.8mA): DC HiPot current 5mA range Full calibration (DC/IR Mode)

- **ARCing Calibration (See 4.4)**
  - AC ARC 20mA (7mA): AC Withstanding Voltage ARCing calibration (AC Mode)
  - DC ARC 5mA (5mA): DC Withstanding Voltage ARCing calibration (DC Mode)

- **Insulation Resistance Calibration (See 4.5)**
  - IRR Range1 (1000MΩ): IR Resistor range 1 calibration (IR Mode)
  - IRR Range2 (100MΩ): IR Resistor range 2 calibration (IR Mode)
  - IRR Range3 (10MΩ): IR Resistor range 3 calibration (IR Mode)
  - IRR Range4 (10MΩ): IR Resistor range 4 calibration (IR Mode)

- **Ground Continue Calibration**
  - GC 5Ω Offset (1Ω): GC 5Ω offset calibration
  - GC 5Ω Full (3Ω): GC 5Ω full calibration
4.1 Calibration

- Press [MENU].
- Press [UP] or [DOWN] to select “CALIBRATION”.
- Press [SELECT].
- Press [A][A][A][B][ENTER].

4.2 Voltage Calibration

4.2.1 Connection Diagram

4.2.2 ACV Calibration (AC Mode)

(1) Press [UP] or [DOWN] to select ACV offset calibration.
(2) Connect an AC high voltage meter to HiPot tester.
(3) Press [STOP][START]; reading the high voltage meter value, ex. 0.052kV.
(4) Press [INC.] or [DEC.] until the Standard Value display 0.052 kV and then press
Calibration Procedure

(5) Press [STOP] to stop ACV voltage offset calibration.
(6) Press [UP] to change to the next calibration item.
(7) Press [STOP][START] to read the high voltage meter value, ex. 4.052kV.

(9) Press [STOP] to stop ACV voltage full scale calibration.

4.2.3 DCV Calibration (DC/IR MODE)

(1) Press [UP] or [DOWN] to select DCV offset calibration.
(2) Connect a DC high voltage meter to HiPot tester.
(3) Press [STOP][START] to read the high voltage meter value, ex. 0.052kV.

(4) Press [INC.][DEC.] until shows 0.052kV and then press [ENTER] for saving.
(5) Press [STOP] to stop DCV voltage offset calibration.
(6) Press [UP] to change to the next calibration item.
(7) Press [STOP][START] to read the high voltage meter value, ex. 4.052kV.
(9) Press [STOP] to stop DCV voltage full scale calibration.

4.2.4 IRV Calibration (DC/IR Mode)

(1) Press [UP] or [DOWN] to select IRV offset calibration.
(2) Connect a DC high voltage meter to HiPot tester.
(3) Press [STOP][START] to read the high voltage meter value, ex. 0.052kV.

(4) Press [INC.] or [DEC.] until shows 0.052 kV and then press [ENTER] for saving.
(5) Press [STOP] to stop IR voltage offset calibration.
(6) Press [UP] to change to the next calibration item.
(7) Press [STOP][START] to read the high voltage meter value, ex. 1.052kV.

(9) Press [STOP] to stop IR voltage full scale calibration.
4.3  Current Calibration

4.3.1 Connection Diagram

Caution
The dummy load connected to HiPot terminal contains high voltage. Be very careful with it as it may cause hazard.

4.3.2 ACA Calibration (AC MODE)

- Connect a dummy load resistor 10MΩ, 0.5 Watt or higher to the HiPot tester between high voltage output terminal and AC ammeter input high potential terminal. Connect the low potential terminal of HiPot tester to the low potential terminal of AC ammeter inputting.
  (1) Press [UP] or [DOWN] to select ACA 3mA range offset calibration.
  (2) Press [STOP][START] to read the ammeter value, ex. 0.124mA.
  (3) Press [INC.] or [DEC.] until shows 0.124mA and then press [ENTER] for saving.
  (4) Press [STOP] to stop ACA 3.0mA range offset calibration.
  (5) Press [UP] to change to the next calibration item.
(6) Change the dummy load resistor to 500kΩ 10watt or higher.
(7) Press [STOP][START] to read the ammeter value, ex. 2.450mA.

(8) Press [INC.] or [DEC.] until shows 2.450mA and then press [ENTER] for saving.
(9) Press [STOP] to stop ACA 3.0mA range full scale calibration.
(10) Press [UP] to change to the next calibration item.
(11) Press [STOP][START] to read the ammeter value, ex. 2.450mA.

(13) Press [STOP] to stop ACA 20.0mA range offset calibration.
(14) Press [UP] to change to the next calibration item.
(15) Change the dummy load resistor to 100kΩ 50watt or higher.
(16) Press [STOP][START] to read the ammeter value, ex. 12.20mA.

(18) Press [STOP] to stop ACA 20.0mA range full scale calibration.
4.3.3 DCA Calibration (DC/IR MODE)

- Connect a dummy load resistor 10MΩ, 0.5 Watt or higher to HiPot tester between high voltage output terminal and DC ammeter input high potential terminal. Connect the low potential terminal of HiPot tester to the low potential terminal of DC ammeter inputting.

1. Press [UP] or [DOWN] to select DCA 3mA range offset calibration.
2. Press [STOP][START] to read the ammeter value, ex. 0.124mA.
3. Press [INC.] or [DEC.] until shows 0.124mA and then press [ENTER] for saving.
4. Press [STOP] to stop DCA 3.0mA range offset calibration.
5. Press [UP] to change to the next calibration item.
6. Change the dummy load resistor to 500kΩ 10watt or higher.
7. Press [STOP][START] to read the ammeter value, ex. 2.450mA.
9. Press [STOP] to stop DCA 3.0mA range full scale calibration.
10. Press [UP] to change to the next calibration item.
11. Press [STOP][START] to read the ammeter value, ex. 2.45mA.
(12) Press [INC.] or [DEC.] until shows 2.45mA and then press [ENTER] for saving.
(13) Press [STOP] to stop DCA 5.0mA range offset calibration.
(14) Press [UP] to change to the next calibration item.
(15) Change the dummy load resistor to 250kΩ 20watt or higher.
(16) Press [STOP][START] to read the ammeter value, ex. 4.85mA.

(18) Press [STOP] to stop DCA 5.0mA range full scale calibration.

### 4.4 ARC Calibration

#### 4.4.1 Connection Diagram
4.4.2 AC ARC Calibration (AC MODE)

Connect one terminal of dummy load resistor 250kΩ, 5 Watt or higher to high voltage output terminal and get closer to low potential terminal of the HiPot tester gradually. However, do not connect the HiPot tester to another terminal of resistor and generate sparking between these two.

(1) Press [UP] or [DOWN] to select AC ARC calibration.
(2) Press [SETUP] [READING] to enter ARC reading setting.
(3) Press [INC.] or [DEC.] until shows the reading is \( \frac{\text{OUTPUT}}{\text{READING}} \times 1.414 \), \( \frac{1.25kV}{250k\Omega} \times 1.414 = 7.7mA \).

(4) Press [RETURN] twice to exit ARC reading setting.
(5) Press [STOP] [START] for starting test.
(6) Press [INC.] or [DEC.] to adjust the low terminal of HiPot tester get closer to another terminal of the dummy load resistor gradually, and generate sparking between these two. The HiPot tester happens ARC fail.
(7) Repeat step (5) – (6) until the sparking between these two is smaller, the HiPot tester still happens ARC fail.

4.4.3 DC ARC Calibration (DC MODE)

Connect one terminal of dummy load resistor 250kΩ, 5 Watt or higher to the high voltage output terminal and get closer to low potential terminal of the HiPot tester gradually. However, do not connect the HiPot tester to another terminal of resistor and generate sparking between these two.

(1) Press [UP] or [DOWN] to select DC ARC calibration.
(2) Press [SETUP] [READING] to enter ARC reading setting.
(3) Press [INC.] or [DEC.] until shows the reading is \( \frac{\text{OUTPUT}}{\text{READING}} \), \( \frac{0.75kV}{250k\Omega} = 3mA \).
(4) Press [RETURN] twice to exit ARC reading setting.
(5) Press [STOP] [START] for starting test.
(6) Press [INC.] or [DEC.] to adjust the low terminal of HiPot tester get closer to another terminal of the dummy load resistor gradually, and generate sparking between these two. The HiPot tester happens ARC fail.
(7) Repeat step (5) – (6) until the sparking between these two is smaller, the HiPot tester still happens ARC fail.

4.5  IRR Calibration (IR Mode)

4.5.1 Connection Diagram

4.5.2 Insulation Resistance Calibration

- Connecting a standard dummy load resistor between the high voltage output terminal and low potential terminal of the Hi-Pot tester.
  - IRR Range1 (1000MΩ) ; the dummy load resistor is 1000MΩ.
  - IRR Range2 (100MΩ) ; the dummy load resistor is 100MΩ.
  - IRR Range3 (10MΩ) ; the dummy load resistor is 10MΩ.
  - IRR Range4 (10MΩ) ; the dummy load resistor is 10MΩ.

(1) Press [UP] or [DOWN] to select IRR range 1 calibration.
(2) To connect the standard dummy load resistor 1000MΩ.
(3) Press [STOP] [START].
(4) Press [INC.] or [DEC.] until shows the standard resistance value, ex. 1000MΩ and then press [ENTER] for saving.
(5) Press [STOP] to stop IRR range 1 calibration.
(6) Press [UP] to change to the next calibration item.
(7) Change the standard dummy load resistor to 100MΩ.
(8) Press [STOP] [START].
(9) Press [INC.] or [DEC.] until shows the standard resistance value, ex. 100MΩ and then press [ENTER] for saving.

<table>
<thead>
<tr>
<th>IRR RANGE 1 (1000MΩ)</th>
<th>60Hz</th>
<th>UP</th>
</tr>
</thead>
<tbody>
<tr>
<td>OUTPUT</td>
<td>READ</td>
<td></td>
</tr>
<tr>
<td>0.250kV 1000MΩ</td>
<td></td>
<td></td>
</tr>
<tr>
<td>STANDARD : 1000MΩ</td>
<td></td>
<td></td>
</tr>
<tr>
<td>LOAD=1000MΩ</td>
<td>RMT</td>
<td>LOCK</td>
</tr>
</tbody>
</table>

(10) Press [STOP] to stop IRR range 2 calibration.
(11) Press [UP] to change to the next calibration item.
(12) Change the standard dummy load resistor to 10MΩ.
(13) Press [STOP] [START].
(14) Press [INC.] or [DEC.] until shows the standard resistance value, ex. 10MΩ and then press [ENTER] for saving.

<table>
<thead>
<tr>
<th>IRR RANGE 2 (100MΩ)</th>
<th>60Hz</th>
<th>UP</th>
</tr>
</thead>
<tbody>
<tr>
<td>OUTPUT</td>
<td>READ</td>
<td></td>
</tr>
<tr>
<td>0.250kV 100MΩ</td>
<td></td>
<td></td>
</tr>
<tr>
<td>STANDARD : 100.0MΩ</td>
<td></td>
<td></td>
</tr>
<tr>
<td>LOAD=100MΩ</td>
<td>RMT</td>
<td>LOCK</td>
</tr>
</tbody>
</table>

(15) Press [STOP] to stop IRR range 3 calibration.
(16) Press [UP] to change to the next calibration item.
(17) Press [STOP] [START].
(18) Press [INC.] or [DEC.] until shows the standard resistance value, ex. 10MΩ and then
press [ENTER] for saving.

<table>
<thead>
<tr>
<th>IRR RANGE4 (10MΩ)</th>
<th>60Hz</th>
<th>UP</th>
</tr>
</thead>
<tbody>
<tr>
<td>OUTPUT</td>
<td></td>
<td>DOWN</td>
</tr>
<tr>
<td>READING</td>
<td>1.000kV</td>
<td>10.0MΩ</td>
</tr>
<tr>
<td>STANDARD: 10.0MΩ</td>
<td></td>
<td>SETUP</td>
</tr>
<tr>
<td>LOAD=10MΩ</td>
<td>RMT</td>
<td>OFST</td>
</tr>
<tr>
<td></td>
<td></td>
<td>ERR</td>
</tr>
</tbody>
</table>

(19) Press [STOP] to stop IRR range 4 calibration.

4.6 Ground Continue Calibration

4.6.1 Connection Diagram

4.6.2 Description of Ground Continue Calibration

- Connect the standard dummy load resistor to the rear panel of HiPot tester which is between ground continue current output terminal and grounding terminal. Using the standard 1Ω and 3Ω 1/8 Watt dummy load resistors.

Preparing a standard 1Ω resistor.
(1) Press [UP].
(2) Connect resistor to ground and CONT.CHECK OPTION terminal of rear panel.
(3) Press [STOP][START] to read GC resistance value 1Ω.
(4) Press [UP] or [DOWN] until the reading is the actual resistance value.
(5) Press [ENTER] for saving the calibration value.
(6) Press [STOP] to stop GC 5Ω Offset calibration.

Change the standard resistor to 3Ω.
(1) Press [UP].
(2) Connect resistor to ground and CONT.CHK OPTION terminal of rear panel.
(3) Press [STOP][START] to read GC resistance value 3Ω.
(4) Press [UP] or [DOWN] until the reading is the actual resistance value.

(5) Press [ENTER] for saving the calibration value.
(6) Press [STOP] to stop GC 5Ω Full calibration.

4.7 LCD Contrast Calibration

- After cleared the memory data, this calibration set LCD Contrast to the best suitable value.
  (2) Press [SETUP] to enter LCD Contrast setting.
  (3) Press [INC.] or [DEC.] until the reading shows the best suitable brightness.
4.8 Complete Calibration

- Press [EXIT] to complete the calibration. Press the front panel calibration switch again for opening the hardware data backup protection circuit to avoid the calibration data loss.
5. **RS485 Interface (For Link Model of 19073 + RS485)**

If link model of 19073 + RS485 is purchased, please refer this chapter.

### 5.1 Description of Function

1. RS485 interface can connect multi-device, and it up to multi-device test synchronously through Master operation.

   ![Diagram of RS485 Interface](image)

   - Master
   - RS485 Bus
   - Slave 1
   - Slave 2
   - Slave n

2. It is able to connect PC from this interface (PC includes RS485 interface). The PC is instead of Master for up to remote control function.

   ![Diagram of PC Connection](image)

   - PC
   - Master
   - RS485 Bus
   - Slave 1
   - Slave 2
   - Slave n

### 5.2 Parameter Setting

1. Press [MENU] under [STANDBY] screen, and by using [F1], [F2] to move the highlight to “OPTION” then press [SELECT]. Move the highlight to [REMOTE INTERFACE], press [SELECT] then can enter RS485 setting screen.
2. Use [NEXT] to move the highlight, and [UP], [DOWN] to switch the setting value.
3. Setting item descriptions:
   a. INTERFACE: It selects if the RS485 interface existed or not.
   b. UNIT TYPE: It selects the device is Master or Slave.
   c. BAUD RATE: It selects the transmission rate is 4800, 9600 or 19200 baud rate.
   d. SLAVE NUMBER (Master Only): When the tester is powered-on or test completed (selectable), Master will detect if address 1 to Slave communication is normal or not.
   e. CHECK RESULT (Master Only): When CHECK RESULT ON, the rear panel
signal meanings of Master are as the following:
UNDER TEST signal: It means Slave in testing.
PASS signal: It means all Slave connections are normal and the test completed.
FAIL signal: It means Slave not complete the test, may be the connections abnormal.

**NOTE:**
When CHECK RESULT ON, Master will not judge the test result of the DUT, thus Master can’t connect the DUT.

4. SEND START (Master Only): It controls that Master receives [START] signal of front panel or rear panel, if it will send the signal to all Slaves through RS485 interface.

**NOTE:**
When the tester power-on, before testing if Slave communication is normal, Master will switch Slave to Remote status in advance. When the test is completed, if this switch (SEND START) set as OFF then Master will switch Slave to Local status.

5. UNIT ADDRESS (Slave Only): It sets Slave address, the range is 1-31 (Master address is fixed on 32).

### 5.3 Terminal and Pin Signal Connection

RS485

![RS485 Diagram](image-url)
5.4 Communication Protocol

This interface uses half duplex of 2-wire system non-synchronized transmission mode.

Before the bus control is transferred, please wait the time of two characters.

<table>
<thead>
<tr>
<th>Master</th>
<th>Slave1</th>
<th>Master</th>
<th>Slave n</th>
</tr>
</thead>
<tbody>
<tr>
<td>n1 Bytes</td>
<td>2 Bytes</td>
<td>n2 Bytes</td>
<td>2 Bytes</td>
</tr>
<tr>
<td>2 Bytes</td>
<td>n3 Bytes</td>
<td>2 Bytes</td>
<td>n4 Bytes</td>
</tr>
</tbody>
</table>

The transmission format of character is 1 initial bit, 8 data bits and 1 end bit, the total is 10 bits.

The receivers don’t respond any data under broadcast mode. When the receivers receive the query functions under node-to-node transmission mode, it returns the relative data. However, the receivers receive the execution command, it returns the result of executing. About Reply Message, please refer the descriptions of command.

The commands are packed into packets, Data Frame as the following:

<table>
<thead>
<tr>
<th>Header</th>
<th>DA</th>
<th>SA</th>
<th>Length</th>
<th>Data Field</th>
<th>Checksum</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 byte</td>
<td>1 byte</td>
<td>1 byte</td>
<td>1 byte</td>
<td>n bytes</td>
<td>1 byte</td>
</tr>
</tbody>
</table>

Header: 0xAB
Destination Address: 0x0 ~ 0x7F, 0xFF is broadcast address
Source Address: 0x0 ~ 0x7F
Data Field Length: It means the length of data field.
Data Field: Please refer the command set.
<table>
<thead>
<tr>
<th>Command Code</th>
<th>Parameter</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 byte</td>
<td>0 ~ n-1 bytes</td>
</tr>
</tbody>
</table>

Checksum: Summing these values into two supplements, included data are DA + SA + Length + Data Field

5.5 Command List

<table>
<thead>
<tr>
<th>Commands</th>
<th>Code (Hex)</th>
</tr>
</thead>
<tbody>
<tr>
<td>*IDN?</td>
<td>0x90</td>
</tr>
<tr>
<td>Display Address</td>
<td>0x20</td>
</tr>
<tr>
<td>Stop</td>
<td>0x21</td>
</tr>
<tr>
<td>Start</td>
<td>0x22</td>
</tr>
<tr>
<td>Offset Get/Off</td>
<td>0x23</td>
</tr>
<tr>
<td>Offset?</td>
<td>0xA3</td>
</tr>
<tr>
<td>Step Parameters</td>
<td>0x24</td>
</tr>
<tr>
<td>Step Parameters?</td>
<td>0xA4</td>
</tr>
<tr>
<td>Preset Parameters</td>
<td>0x25</td>
</tr>
<tr>
<td>Preset Parameters?</td>
<td>0xA5</td>
</tr>
<tr>
<td>Store Memory</td>
<td>0x26</td>
</tr>
<tr>
<td>Recall Memory</td>
<td>0x27</td>
</tr>
<tr>
<td>Delete Memory</td>
<td>0x28</td>
</tr>
<tr>
<td>System Setting</td>
<td>0x29</td>
</tr>
<tr>
<td>System Setting?</td>
<td>0xA9</td>
</tr>
<tr>
<td>Key Lock</td>
<td>0x2A</td>
</tr>
<tr>
<td>Key Lock?</td>
<td>0xAA</td>
</tr>
<tr>
<td>Initialize All Steps Parameters</td>
<td>0x2C</td>
</tr>
<tr>
<td>Step Number?</td>
<td>0xAD</td>
</tr>
<tr>
<td>Remote/Local</td>
<td>0x2E</td>
</tr>
<tr>
<td>Remote?</td>
<td>0xAE</td>
</tr>
<tr>
<td>Result?</td>
<td>0xB1</td>
</tr>
<tr>
<td>Reply Message</td>
<td>0x7F</td>
</tr>
</tbody>
</table>

5.6 Command Description

*IDN?  
Description: It queries the devices’ identification and describes the string.  
Command code: 0x90  
Parameter: None  
Return data: The format is "Company Name, Device Name, Device S/N, Firmware Version, Hold Field"  
Example:  
Master (0x70): 0xAB 0x01 0x70 0x01 0x90 0xFE  
Slave (0x01): 0xAB 0x70 0x01 0x16 0x90 0x43 0x48 0x52 0x4F 0x4D 0x41 0x2C 0x31 0x39 0x30 0x37 0x33 0x2C 0x30 0x2C 0x33 0x2E 0x30 0x37 0x2C 0x30 0x53
Descriptions of example
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Data Field Length
0x90 = Command Code
0xFE = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x16 = Data Field Length
0x90 = Command Code
0x43 0x48 0x52 0x4F 0x4E 0x4D 0x41 = “CHROMA” Company Name (return data)
0x2C = “,” (return data)
0x31 0x39 0x30 0x37 0x33 = “19073” Device Name (return data)
0x2C = “,” (return data)
0x30 = “0” Device S/N (return data)
0x2C = “,” (return data)
33 2E 30 37 = “3.07” Firmware Version (return data)
0x2C = “,” (return data)
30 = “0”Hold Field (return data)
0x53 = Checksum

Display Address
Description: It displays the device address.
Command code: 0x20
Parameter: None
Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x01 0x20 0x6E
Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

Descriptions of example
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Source Address
0x20 = Command Code
0x6E = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Source Address
0x7F = Reply Message Command Code
Stop

Description: Stop test
Command code: 0x21
Parameter: None
Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x01 0x21 0x6D
Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

Descriptions of example
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Data Field Length
0x21 = Command Code
0x6D = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

Start

Description: Start test
Command code: 0x22
Parameter: None
Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x01 0x22 0x6C
Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

Descriptions of example
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Data Field Length
0x22 = Command Code
0x6C = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

**Offset Get/Off**
Description: It switches OFFSET status.
Command code: 0x23
Parameter: 1 byte, 0:OFF or 2:GET
Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x02 0x23 0x02 0x68
Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x02 = Data Field Length
0x23 = Command Code
0x02 = 2:GET (Command Parameter)
0x68 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

**Offset?**
Description: It queries OFFSET status.
Command code: 0xA3
Parameter: None
Return data: 1 byte, 0: Off, 1: On or 2: Getting
Example: Master (0x70): 0xAB 0x01 0x70 0x01 0xA3 0xEB
Slave (0x01): 0xAB 0x70 0x01 0x02 0xA3 0x00 0xEA

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Data Field Length
0xA3 = Command Code
0xEB = Checksum
The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0xA3 = Command Code
0x00 = 0: Off (Return Data)
0xEA = Checksum

**Step Parameters**
Description: It sets all parameters of various steps.
Command code: 0x24
Parameter: 28 bytes

### AC mode

<table>
<thead>
<tr>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Range</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step index</td>
<td>1</td>
<td>-</td>
<td>1~10</td>
<td>Must less or equal original step number + 1</td>
</tr>
<tr>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>1</td>
<td>AC mode</td>
</tr>
<tr>
<td>Source</td>
<td>2</td>
<td>V</td>
<td>0, 50~5000</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Ramp Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Reserved</td>
<td>2</td>
<td>-</td>
<td>0</td>
<td>Reserved</td>
</tr>
<tr>
<td>Test Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:Continue</td>
</tr>
<tr>
<td>Fall Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:OFF</td>
</tr>
<tr>
<td>High Limit</td>
<td>4</td>
<td>100nA</td>
<td>10~200000</td>
<td></td>
</tr>
<tr>
<td>Low Limit</td>
<td>4</td>
<td>100nA</td>
<td>0, 10~200000</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Arc Limit</td>
<td>4</td>
<td>100nA</td>
<td>0, 10000~200000</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Reserved</td>
<td>4</td>
<td>-</td>
<td>0</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

### DC Mode

<table>
<thead>
<tr>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Range</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step index</td>
<td>1</td>
<td>-</td>
<td>1~10</td>
<td>Must less or equal original step number + 1</td>
</tr>
<tr>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>2</td>
<td>DC mode</td>
</tr>
<tr>
<td>Source</td>
<td>2</td>
<td>V</td>
<td>0, 50~6000</td>
<td></td>
</tr>
<tr>
<td>Ramp Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Dwell Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Test Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:Continue</td>
</tr>
<tr>
<td>Fall Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:OFF</td>
</tr>
<tr>
<td>High Limit</td>
<td>4</td>
<td>100nA</td>
<td>1~50000</td>
<td></td>
</tr>
<tr>
<td>Low Limit</td>
<td>4</td>
<td>100nA</td>
<td>0~50000</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Arc Limit</td>
<td>4</td>
<td>100nA</td>
<td>0, 10000~50000</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Inrush Limit</td>
<td>4</td>
<td>100nA</td>
<td>0, 5~50000</td>
<td>0:OFF</td>
</tr>
</tbody>
</table>

### IR Mode

<table>
<thead>
<tr>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Range</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step index</td>
<td>1</td>
<td>-</td>
<td>1~10</td>
<td>Must less or equal original step number + 1</td>
</tr>
<tr>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>3</td>
<td>IR mode</td>
</tr>
<tr>
<td>Source</td>
<td>2</td>
<td>V</td>
<td>0, 50~1000</td>
<td></td>
</tr>
<tr>
<td>Ramp Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Dwell Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Test Time</td>
<td>2</td>
<td>100mS</td>
<td>0, 3~9990</td>
<td>0:Continue</td>
</tr>
<tr>
<td>Fall Time</td>
<td>2</td>
<td>100mS</td>
<td>0~9990</td>
<td>0:OFF</td>
</tr>
<tr>
<td>High Limit</td>
<td>4</td>
<td>100kOhm</td>
<td>0~500000</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Low Limit</td>
<td>4</td>
<td>100kOhm</td>
<td>1~500000</td>
<td></td>
</tr>
</tbody>
</table>
Reserved | 4 | - | 0 | Reserved
Reserved | 4 | - | 0 | Reserved

### GC Mode

<table>
<thead>
<tr>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Range</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step index</td>
<td>1</td>
<td>-</td>
<td>1~10</td>
<td>Must less or equal original step number + 1</td>
</tr>
<tr>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>4</td>
<td>GC mode</td>
</tr>
<tr>
<td>Source</td>
<td>2</td>
<td>mA</td>
<td>0/100</td>
<td></td>
</tr>
<tr>
<td>Reserved</td>
<td>2</td>
<td>-</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>Dwell Time</td>
<td>2</td>
<td>100mS</td>
<td>1~10</td>
<td></td>
</tr>
<tr>
<td>Reserved</td>
<td>2</td>
<td>-</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>High Limit</td>
<td>4</td>
<td>100mOhm</td>
<td>1~50</td>
<td></td>
</tr>
<tr>
<td>Low Limit</td>
<td>4</td>
<td>100mOhm</td>
<td>0~50</td>
<td>0:OFF</td>
</tr>
<tr>
<td>Reserved</td>
<td>4</td>
<td>-</td>
<td>0</td>
<td></td>
</tr>
</tbody>
</table>

### PA Mode (Pause mode)

<table>
<thead>
<tr>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Range</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step index</td>
<td>1</td>
<td>-</td>
<td>1~10</td>
<td>Must less or equal original step number + 1</td>
</tr>
<tr>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>5</td>
<td>PA mode</td>
</tr>
<tr>
<td>UT Signal</td>
<td>2</td>
<td>-</td>
<td>1 or 2</td>
<td>(Under Test Signal) 1:Off, 2:On</td>
</tr>
<tr>
<td>Message</td>
<td>16</td>
<td>-</td>
<td>C String, maximum length is 15</td>
<td></td>
</tr>
<tr>
<td>Reserved</td>
<td>4</td>
<td>-</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>Reserved</td>
<td>4</td>
<td>-</td>
<td>0</td>
<td></td>
</tr>
</tbody>
</table>

Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x1D 0x24 0x01 0x01 0xE8 0x03 0x14 0x00 0x00 0x00 0x32 0x00 0x01E 0x00 0x10 0x27 0x00 0x00 0x00 0x00 0x00 0xE8 0x03 0x00 0x00 0x10 0x27 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0xA4
Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E
Remark: When the length of data is larger than 1 character (byte), it is need to send the minimum character in advance.

Descriptions of example
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x1D = Data Field Length
0x24 = Command Code
0x01 = Step1 (Command Parameter)
0x01 = AC Mode (Command Parameter)
0xE8 0x03 = Voltage 1000V (Command Parameter)
0x14 0x00 = Ramp Time 2sec (Command Parameter)
0x14 0x00 = Reserved (Command Parameter)
0x10 0x00 = Reserved (Command Parameter)
0x32 0x00 = Test Time 5sec (Command Parameter)
0xE8 0x03 0x00 0x00 = Hi Limit 1.000mA (Command Parameter)
0xE8 0x03 0x00 0x00 = Low Limit 0.100mA (Command Parameter)
0xE8 0x03 0x00 0x00 = Arc Limit 1.000mA (Command Parameter)
0x00 0x00 0x00 0x00 = Reserved (Command Parameter)
0x0E = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

**Step Parameters?**

Description: It queries all parameters of various steps.
Command code: 0xA4
Parameter: 1 byte, the serial number of step, the range is 1-10
Return data: 28 bytes data
Example: Master (0x70): 0xAB 0x01 0x70 0x02 0xA4 0x01 0xE8
Slave (0x01): 0xAB 0x70 0x01 0x1D 0xA4 0x01 0x01 0x38 0xE4 0x1E 0x00 0x00 0x00 0x3C 0x00 0x09 0x00 0x20 0x4E 0x00 0x00 0x00 0x0B

**Descriptions of example**

The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x02 = Data Field Length
0xA4 = Command Code
0x01 = Parameter
0xE8 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x1D = Data Field Length
0xA4 = Command Code
0x01 = Step1 (Return Data)
0x01 = AC Mode (Return Data)
0x38 0x04 = Voltage 1080V (Return Data)
0x1E 0x00 = Ramp Time 3sec (Return Data)
0x00 0x00 = Reserved (Return Data)
0x3C 0x00 = Test Time 6sec (Return Data)
0x09 0x00 = Fall Time 0.9sec (Return Data)
0x0C 0x17 0x00 0x00 = Hi Limit 0.590mA (Return Data)
0x90 0x01 0x00 0x00 = Low Limit 0.040mA (Return Data)
0x20 0x4E 0x00 0x00 = Arc Limit 2.000mA (Return Data)
0x00 0x00 0x00 0x00 = Reserved (Return Data)
0x0B = Checksum

**Preset Parameters**

*Description:* It sets all parameters of Preset.

*Command code:* 0x25

*Parameter:* 6 bytes

<table>
<thead>
<tr>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Range</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AC Frequency</td>
<td>1</td>
<td>Hz</td>
<td>50/60</td>
<td></td>
</tr>
<tr>
<td>Software AGC</td>
<td>1</td>
<td>-</td>
<td>0/1</td>
<td>0:OFF, 1:ON</td>
</tr>
<tr>
<td>WV Auto Range</td>
<td>1</td>
<td>-</td>
<td>0/1</td>
<td>0:OFF, 1:ON</td>
</tr>
<tr>
<td>IR Auto Range</td>
<td>1</td>
<td>-</td>
<td>0/1</td>
<td>0:OFF, 1:ON</td>
</tr>
<tr>
<td>Fail Restart</td>
<td>1</td>
<td>-</td>
<td>0/1</td>
<td>0:OFF, 1:ON</td>
</tr>
<tr>
<td>Ground Fault Interrupt</td>
<td>1</td>
<td>-</td>
<td>0/1</td>
<td>0:OFF, 1:ON</td>
</tr>
</tbody>
</table>

Return data: Reply Message

Example:
Master (0x70): 0xAB 0x01 0x70 0x07 0x25 0x32 0x00 0x01 0x00 0x00 0x01 0x2F
Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

**Descriptions of example**

The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x07 = Data Field Length
0x25 = Command Code
0x32 = ACV Frequency 50Hz
0x00 = Software AGC OFF
0x01 = WV Auto Range ON
0x00 = IR Auto Range OFF
0x00 = Fail Restart ON
0x01 = Ground Fault Interrupt ON
0x2F = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

**Preset Parameter?**

*Description:* It queries all parameters of Preset.

*Command code:* 0xA5

*Parameter:* None
Return data: 6 bytes
Example: Master (0x70): 0xAB 0x01 0x70 0x01 0xA5 0xE9
           Slave (0x01): 0xAB 0x70 0x01 0x07 0xA5 0x3C 0x01 0x00 0x01
                  0x01 0x00 0xA4

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Data Field Length
0xA5 = Data Field Length
0xE9 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x07 = Data Field Length
0xA5 = Command Code
0x3C = ACV Frequency 60Hz (Return Data)
0x01 = Software AGC ON (Return Data)
0x00 = WV Auto Range OFF (Return Data)
0x01 = IR Auto Range ON (Return Data)
0x01 = Fail Restart OFF (Return Data)
0x00 = Ground Fault Interrupt OFF (Return Data)
0xA4 = Checksum

**Store Memory**
Description: It saves the parameters of various steps and Preset to the internal memory.
Command code: 0x26
Parameter: Serial number of memory + Name of memory. The length of serial number of memory is 1 character. The range is 1 ~ 60, the name length of the memory is 0 ~ 10 character.
Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x08 0x26 0x01 0x43 0x48 0x52
         0x4F 0x4D 0x41 0xA6
           Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x08 = Data Field Length
0x26 = Command Code
0x01 = Memory S/N
RS485 Interface (For Link Model of 19073 + RS485)

0x43 0x48 0x52 0x4F 0x4D 0x41 = "CHROMA" Memory Name
(Command Parameter)
0xA6 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

Recall Memory
Description: It recalls the saved test steps from various device internal memories.
Command code: 0x27
Parameter: 1 byte, serial number of memory, the range is 1 ~ 60
Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x02 0x27 0x01 0x65
               Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

Descriptions of example
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x02 = Data Field Length
0x27 = Command Code
0x01 = “01” Memory S/N (Command Parameter)
0x65 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

Delete Memory
Description: It deletes the saved test steps from the memories inside device.
Command code: 0x28
Parameter: 1 byte, serial number of memory, the range is 0 ~ 60. When the parameter is 0, it means it is need to clear the working memory, this includes all steps and Preset parameters.
Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x02 0x28 0x01 0x64
               Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E
Descriptions of example
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x02 = Data Field Length
0x28 = Command Code
0x01 = “01” Memory S/N (Command Parameter)
0x64 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

System Setting
Description: It sets the system parameter.
Command code: 0x29
Parameter: 4 bytes

<table>
<thead>
<tr>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Range</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Contrast</td>
<td>1</td>
<td>-</td>
<td>1~15</td>
<td></td>
</tr>
<tr>
<td>Buzzer Volume</td>
<td>1</td>
<td>-</td>
<td>0/1/2/3</td>
<td>0:OFF, 1:Low, 2:Medium, 3:High</td>
</tr>
<tr>
<td>EN50191</td>
<td>1</td>
<td>-</td>
<td>0/1</td>
<td>0:OFF, 1:ON (AC maximum is 3mA)</td>
</tr>
<tr>
<td>DC 50V AGC</td>
<td>1</td>
<td>-</td>
<td>0/1</td>
<td>0:OFF, 1:ON</td>
</tr>
</tbody>
</table>

Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x05 0x29 0x0A 0x03 0x00 0x00 0x54
         Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

Descriptions of example
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x05 = Data Field Length
0x29 = Command Code
0x0A = Contrast 10 (Command Parameter)
0x03 = Buzzer Volume High (Command Parameter)
0x00 = EN50191 OFF (Command Parameter)
0x00 = DC 50V AGC OFF (Command Parameter)
0x64 = Checksum
The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

**System Setting?**
Description: It queries the system parameter.
Command code: 0xA9
Parameter: None
Return data: 4 bytes
Example:
Master (0x70): 0xAB 0x01 0x70 0x01 0xA9 0xE5
Slave (0x01): 0xAB 0x70 0x01 0x05 0xA9 0x08 0x01 0x01 0x01 0xD6

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x01 = Data Field Length
0xA9 = Command Code
0xE5 = Checksum
The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x05 = Data Field Length
0xA9 = Command Code
0x08 = Contrast 8 (Return Data)
0x03 = Buzzer Volume Low (Return Data)
0x00 = EN50191 ON (Return Data)
0x00 = DC 50V AGC ON (Return Data)
0xD6 = Checksum

**Key Lock**
Description: It switches KEY LOCK status.
Command code: 0x2A
Parameter: 1 byte
0: key board lock OFF, recall key lock OFF
1: key board lock ON, recall key lock OFF
2: key board lock ON, recall key lock ON
Return data: Reply Message
Example:
Master (0x70): 0xAB 0x01 0x70 0x02 0x2A 0x01 0x62
Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E
**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x02 = Data Field Length
0x2A = Command Code
0x01 = “01”key board lock ON, recall key lock (Command Parameter)
0x62 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

---

**Key Lock?**
Description: It queries KEY LOCK status.
Command code: 0xAA
Parameter: None
Return data: 1 byte data
0: keyboard lock OFF, recall key lock OFF
1: keyboard lock ON, recall key lock OFF
2: keyboard lock ON, recall key lock ON

Example: Master (0x70): 0xAB 0x01 0x70 0x01 0xAA 0xE4
Slave (0x01): 0xAB 0x70 0x01 0x02 0xAA 0x01 0xE2

---

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Data Field Length
0xAA = Command Code
0xE4 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0xAA = Command Code
0x01 = “01”Key Board Lock ON, Recall Key Lock OFF (Return Data)
0XE2 = Checksum
**Initialize All Steps Parameters**

Description: It sets all steps to the initial setting, this command will delete all steps.
Command code: 0x2C
Parameter: None
Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x01 0x2C 0x62
          Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Data Field Length
0x2C = Command Code
0x62 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

**Step Number?**

Description: It queries the step numbers of being set.
Command code: 0xAD
Parameter: None
Return data: 1 byte data
Example: Master (0x70): 0xAB 0x01 0x70 0x01 0xAD 0xE1
          Slave (0x01): 0xAB 0x70 0x01 0x02 0xAD 0x05 0xDB

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Data Field Length
0xAD = Command Code
0xE1 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0xAD = Command Code
0x05 = “05” the step numbers of being set (Return Data)
0xDB = Checksum

**Remote/Local**

Description: It switches the device to remote or local control.
Command code: 0x2E
Parameter: 1 byte
0: Go to Local.
1: Go to Remote.
2: Go to Remote and Local Lockout
Return data: Reply Message
Example: Master (0x70): 0xAB 0x01 0x70 0x02 0x2E 0x01 0x5E
Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x02 = Data Field Length
0x2C = Command Code
0x01 = “1” Go to Remote (Command Parameter)
0x62 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Reply Message Command Code
0x00 = Reply Message Return Data
0x0E = Checksum

**Remote Status?**

Description: It queries remote status of the device.
Command code: 0xAE
Parameter: None
Return data: 1 byte data
0: Local
1: Remote
2: Remote and Local Lockout
Example: 0xAB 0x01 0x70 0x00 0xAE 0x01 0xDE

**Descriptions of example**
The setting meanings of HEX inputs are as the following:
0xAB = Header
0x01 = Destination Address
0x70 = Source Address
0x01 = Data Field Length
0xAB = Command Code
0xE0 = Checksum

The reading meanings of returning HEX code are as the following:
0xAB = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0xAE = Command Code
0x00 = “1” Remote (Return Data)
0xDE = Checksum

Result?
Description: It queries the test result and measurement value.
Command code: 0xB1
Parameter: 2 bytes, serial numbers of steps + items of measurement values, the range of serial numbers of steps is 0 ~ 10. When the range is 0, it means to query the last one which starts to perform or the step which be performed completely. According to the weight of 2 to divide the measurement value option into 8 items, if queries multi-item simultaneously, the lesser weight is sent at first.

The measurement value option:

<table>
<thead>
<tr>
<th>Item Number</th>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>AC mode</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>1:AC Mode</td>
</tr>
<tr>
<td>2</td>
<td>Meter 1 (Source)</td>
<td>2</td>
<td>V</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>4</td>
<td>Meter 2 (Current)</td>
<td>4</td>
<td>100nA</td>
<td>1000000000: Maximum, 1100000000: Not Value</td>
</tr>
<tr>
<td>8</td>
<td>Meter 3</td>
<td>4</td>
<td>-</td>
<td>Reserved</td>
</tr>
<tr>
<td>16</td>
<td>Ramp Time</td>
<td>2</td>
<td>100mS</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>32</td>
<td>Reserved</td>
<td>2</td>
<td>-</td>
<td>Reserved</td>
</tr>
<tr>
<td>64</td>
<td>Test Time</td>
<td>2</td>
<td>100mS</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>128</td>
<td>Fall Time</td>
<td>2</td>
<td>100mS</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td><strong>DC mode</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>2:DC Mode</td>
</tr>
<tr>
<td>2</td>
<td>Meter 1 (Source)</td>
<td>2</td>
<td>V</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>4</td>
<td>Meter 2 (Current)</td>
<td>4</td>
<td>100nA</td>
<td>1000000000: Maximum, 1100000000: Not Value</td>
</tr>
<tr>
<td>8</td>
<td>Meter 3 (Inrush)</td>
<td>4</td>
<td>100nA</td>
<td>1000000000: Maximum, 1100000000: Not Value</td>
</tr>
<tr>
<td>16</td>
<td>Ramp Time</td>
<td>2</td>
<td>100mS</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>32</td>
<td>Dwell Time</td>
<td>2</td>
<td>100mS</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>64</td>
<td>Test Time</td>
<td>2</td>
<td>100mS</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>128</td>
<td>Fall Time</td>
<td>2</td>
<td>100mS</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td><strong>IR mode</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>3:IR Mode</td>
</tr>
<tr>
<td>2</td>
<td>Meter 1 (Source)</td>
<td>2</td>
<td>V</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>4</td>
<td>Meter 2 (Resistance)</td>
<td>4</td>
<td>100kOhm</td>
<td>1000000000: Maximum, 1100000000: Not Value</td>
</tr>
</tbody>
</table>
### GC mode

<table>
<thead>
<tr>
<th>Item Number</th>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>4:GC Mode</td>
</tr>
<tr>
<td>2</td>
<td>Meter 1 (Source)</td>
<td>2</td>
<td>mA</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>4</td>
<td>Meter 2 (Resistance)</td>
<td>4</td>
<td>100mOhm</td>
<td>100000000000: Maximum, 11000000000: Not Value</td>
</tr>
<tr>
<td>8</td>
<td>Meter 3</td>
<td>4</td>
<td>-</td>
<td>Reserved</td>
</tr>
<tr>
<td>16</td>
<td>Reserved</td>
<td>2</td>
<td>-</td>
<td>Reserved</td>
</tr>
<tr>
<td>32</td>
<td>Dwell Time</td>
<td>2</td>
<td>100mS</td>
<td>30000: Maximum, 31000: Not Value</td>
</tr>
<tr>
<td>64</td>
<td>Reserved</td>
<td>2</td>
<td>-</td>
<td>Reserved</td>
</tr>
<tr>
<td>128</td>
<td>Reserved</td>
<td>2</td>
<td>-</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

### PA mode

<table>
<thead>
<tr>
<th>Item Number</th>
<th>Name</th>
<th>Size (byte)</th>
<th>Unit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Mode</td>
<td>1</td>
<td>-</td>
<td>5:PA Mode</td>
</tr>
<tr>
<td>2</td>
<td>Under Test Signal</td>
<td>2</td>
<td>-</td>
<td>1:Off, 2:On</td>
</tr>
<tr>
<td>4, 8, 16, 32, 64 or 128</td>
<td>Message</td>
<td>16</td>
<td>-</td>
<td>C String, maximum length is 15</td>
</tr>
</tbody>
</table>

Return data: The flag of new test result (1 byte) + serial number of step (1 byte) + test result (1 byte) + measurement value option (1 byte) [ + measurement value 1 + measurement value 2 + …]

The flag is with new test result: it is the correct flag that can judge the measurement result. This flag set as ON when the test is initiated, and set as OFF when the test is stopped. Alternatively, the test is ended and the result is read by this command, then set as OFF. Thus, only in the test duration, the test completed or uses this command to read first time, this flag is ON otherwise is OFF.
## Return test result codes:

<table>
<thead>
<tr>
<th>Mode</th>
<th>AC</th>
<th>DC</th>
<th>IR</th>
<th>GC</th>
<th>ALL</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>HEX</td>
<td>DEC</td>
<td>HEX</td>
<td>DEC</td>
<td>HEX</td>
</tr>
<tr>
<td>STOP</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>70</td>
</tr>
<tr>
<td>USER</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>71</td>
</tr>
<tr>
<td>INTERRUPT</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>72</td>
</tr>
<tr>
<td>CAN NOT TEST</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>73</td>
</tr>
<tr>
<td>TESTING PASS SKIP</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>74</td>
</tr>
<tr>
<td>GFI FAIL</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>75</td>
</tr>
<tr>
<td>HIGH FAIL</td>
<td>11</td>
<td>17</td>
<td>21</td>
<td>33</td>
<td>41</td>
</tr>
<tr>
<td>LOW FAIL</td>
<td>12</td>
<td>18</td>
<td>22</td>
<td>34</td>
<td>42</td>
</tr>
<tr>
<td>ARC FAIL</td>
<td>13</td>
<td>19</td>
<td>23</td>
<td>35</td>
<td></td>
</tr>
<tr>
<td>I/O FAIL</td>
<td>14</td>
<td>20</td>
<td>24</td>
<td>36</td>
<td>34</td>
</tr>
<tr>
<td>NO OUTPUT OVER</td>
<td>15</td>
<td>21</td>
<td>25</td>
<td>37</td>
<td>35</td>
</tr>
<tr>
<td>VOLTAGE CURRENT</td>
<td>16</td>
<td>22</td>
<td>26</td>
<td>38</td>
<td>36</td>
</tr>
<tr>
<td></td>
<td>17</td>
<td>23</td>
<td>27</td>
<td>39</td>
<td>37</td>
</tr>
<tr>
<td>INRUSH FAIL</td>
<td>28</td>
<td>40</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Example: The test results of devices:

- Master (0x70): 0xAB 0x01 0x70 0x03 0xB1 0x00 0xD7 0xE0
- Slave (0x01): 0xAB 0x70 0x01 0x12 0xB1 0x01 0x74 0xD7 0x01
  - 0x63 0x00 0x5A 0x00 0x00 0x00 0x0F 0x00 0x1E 0x00
  - 0x18 0x00 0x7C

### Descriptions of example

The setting meanings of HEX inputs are as the following:

- 0xAB = Header
- 0x01 = Destination Address
- 0x70 = Source Address
- 0x03 = Data Field Length
- 0xB1 = Command Code
- 0x00 = “00“ It queries the last step that begins to execute or have been executed.
  (Command Parameter)
- 0xD7 = “D7“ Item Number (Command Parameter)
- 0xE0 = Checksum

The reading meanings of returning HEX code are as the following:

- 0xAB = Header
- 0x70 = Destination Address
- 0x01 = Source Address
- 0x12 = Data Field Length
- 0xB1 = Command Code
- 0x01 = New test result (Return Data)
0x01 = Step1 (Return Data)
0x74 = Test result code ”PASS” (Return Data)
0xD7 = Item number (Return Data)
0x01 = AC mode (Return Data)
0x63 0x00 = Display Volt 0.100kV (Return Data)
0x5A 0x00 0x00 0x00 = Curr 0.009mA (Return Data)
0x0F 0x00 = ramp time 1.5sec (Return Data)
0x1E 0x00 = test time 3.0sec (Return Data)
0x18 0x00 = fall time 2.4sec (Return Data)
0x7C = Checksum

Φ Note:  
When the tester is pause mode, the data field length of returning may be different from other modes.

Reply Message
Description: It queries the performed result of previous command.
Command code: 0x7F
Parameter: None
Return data: 1 byte
0 – OK, no error
1 – Command Error (Include Execution Error)
2 – Parameter Error
Example: Relay Message Return Data
Slave (0x01): 0xAB 0x70 0x01 0x02 0x7F 0x00 0x0E

Descriptions of example
The reading meanings of returning HEX code are as the following:
0x0F = Header
0x70 = Destination Address
0x01 = Source Address
0x02 = Data Field Length
0x7F = Command Code
0x00 = “00”OK, no error (Return Data)
0x0E = Checksum
5.7 Flow Diagram

1. Confirm if all of Slaves’ communication is normal or not:

   ![Flow Diagram Diagram]

   - Power Up
   - Set x to 1
   - Send “Display Address” command (command code: 0x20) for slave x
   - Return OK message?
   - x add 1
   - All slaves finished
   - Standby
   - Yes
   - Yes
   - No
   - Alarm
   - 5-23
2. Upload the test steps from one slave then download to all slaves.
3. Read the measurement data:

```
Has Test Data?  
  Yes
  Set x to 1  
  (x is the slave address that will send data)  
  Send "Result?" command (command code: 0xB1) for slave x
  Has New Data?  
    Yes
    x add 1
    All slaves finished Standby
    Yes
    No
    Alarm
    No
    Test Finished
    No
    Store Data
```


6. Maintenance

6.1 General

Our warranty (at the front of the manual) attests the quality of materials and workmanship in our products. If malfunction should be suspected, or other information be desired applications engineers are available for technical assistance. Application assistance is available in Taiwan by calling 886-2-22983855 and asking for applications support. For support outside of Taiwan please contact your local Chroma distributor.

6.2 Instrument Return

Before returning an instrument to Chroma for service please call our Service Department at 886-2-22983855 for return material authorization. It will be necessary to include a purchase order number to ensure expedient processing, although units found to be in warranty period will be repaired at no-charge. For any questions on repair costs or shipment instructions please contact our service department at the above number. To safeguard an instrument during storage and shipping please use packaging that is adequate to protect it from damage, i.e., equivalent to the original packaging and mark the box "Delicate Electronic Instrument". Return material should be sent freight prepaid, to:

Chroma Ate Inc.
No.43, Wu-chuan Rd., Wu-ku Ind.Park,
Wu-ku, Taipei Hsien, Taiwan
Attention: Service Department